

FRONT AXLE & FRONT SUSPENSION

SECTION

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Supplemental Restraint System (SRS) "AIR BAG" and "SEAT BELT PRE-TENSIONER"

The Supplemental Restraint System such as "AIR BAG" and "SEAT BELT PRE-TENSIONER" used along with a seat belt, helps to reduce the risk or severity of injury to the driver and front passenger for certain types of collision. The SRS system composition which is available to INFINITI Q45 is as follows:

• For a frontal collision

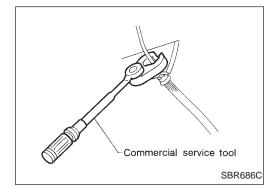
The Supplemental Restraint System consists of driver air bag module (located in the center of the steering wheel), front passenger air bag module (located on the instrument panel on passenger side), seat belt pre-tensioners, a diagnosis sensor unit, warning lamp, wiring harness and spiral cable.

• For a side collision

The Supplemental Restraint System consists of front side air bag module (located in the outer side of front seat), satellite sensor, diagnosis sensor unit (one of components of air bags for a frontal collision), wiring harness, warning lamp (one of components of air bags for a frontal collision).

Information necessary to service the system safely is included in the **RS section** of this Service Manual. **WARNING:**

- To avoid rendering the SRS inoperative, which could increase the risk of personal injury or death in the event of a collision which would result in air bag inflation, all maintenance should be performed by an authorized INFINITI dealer.
- Improper maintenance, including incorrect removal and installation of the SRS, can lead to personal injury caused by intentional activation of the system. For removal of Spiral Cable and Air Bag Module, see the RS section.
- Do not use electrical test equipment on any circuit related to the SRS unless instructed to in this Service Manual. Spiral cable and wiring harnesses covered with yellow insulation tape (except satellite sensor and side air bag module) either just before the harness connectors or for the complete harness are related to the SRS.



Precautions for Brake System

- When installing rubber parts, final tightening must be carried out under unladen condition* with tires on ground.
 - *: Fuel, radiator coolant and engine oil full. Spare tire, jack, hand tools and mats in designated positions.
- After installing removed suspension parts, check wheel alignment and adjust if necessary.
- Use flare nut wrench when removing or installing brake tubes.
- Always torque brake lines when installing.



Special Service Tools

The actual shapes of Kent-Moore tools may differ from those of special service tools illustrated here.

Tool number (Kent-Moore No.) Tool name	Description		G]
ST29020001 (J24319-01) Pitman arm puller		Removing tie-rod outer end and lower ball joint	MA EM
	NT694	a: 34 mm (1.34 in) b: 6.5 mm (0.256 in) c: 61.5 mm (2.421 in)	LC
KV991040S0 (—) C.C.K. holder KV99104010		Attaching wheel alignment gauge	EC
Attachment set Plate 	2 5		FE
 ② Guide bolts ③ Nuts ④ Springs ⑤ Center plate 	O Dunne		AT
 (6) KV99104020 Adapter A (7) KV99104030 	6 Duning - Our		PD
Adapter B (8) KV99104040			FA
Adapter C (9) KV99104050 Adapter D		a: 72 mm (2.83 in) dia. b: 65 mm (2.56 in) dia. c: 57 mm (2.24 in) dia.	RA
ST35490001	NT498 D V	d: 53.4 mm (2.102 in) dia. Removing and installing gland packing	BR
(J26083) Gland packing wrench		Kontoning and instanting giand paoking	ST
	NT383	a: 58 mm (2.28 in) b: 100 mm (3.94 in)	RS
ST35652000 (—) Strut attachment		Fixing strut assembly	BT
	NT145		HA
	1		EL

IDX



Commercial Service Tools

Tool name	Description	
 Flare nut crowfoot Torque wrench 		Removing and installing each brake piping
	NT360 2	a: 10 mm (0.39 in)
Front axle grease seal drift	TIO	Installing front axle grease seal
	a b 1	a: 75 mm (2.95 in) dia. b: 65 mm (2.56 in) dia.
Tension rod bushing drift		Removing and installing tension rod bushing
	NT155	a: 75 mm (2.95 in) dia. b: 66 mm (2.60 in) dia. c: 62 mm (2.44 in) dia. d: 25 - 55 mm (0.98 - 2.17 in) dia.
Wheel bearing drift		Removing wheel bearing
	NT084	a: 49 mm (1.93 in) dia. b: 41 mm (1.61 in) dia.
Wheel bearing drift	T.TO	Installing wheel bearing
	a NT115	a: 66 mm (2.60 in) dia. b: 60 mm (2.36 in) dia.
Cap drift		Installing hub cap
	NT115	a: 77 mm (3.03 in) dia. b: 55.5 mm (2.185 in) dia.
Spring compressor	NTZ1Z	Removing and installing coil spring
	NT717	



NVH Troubleshooting Chart

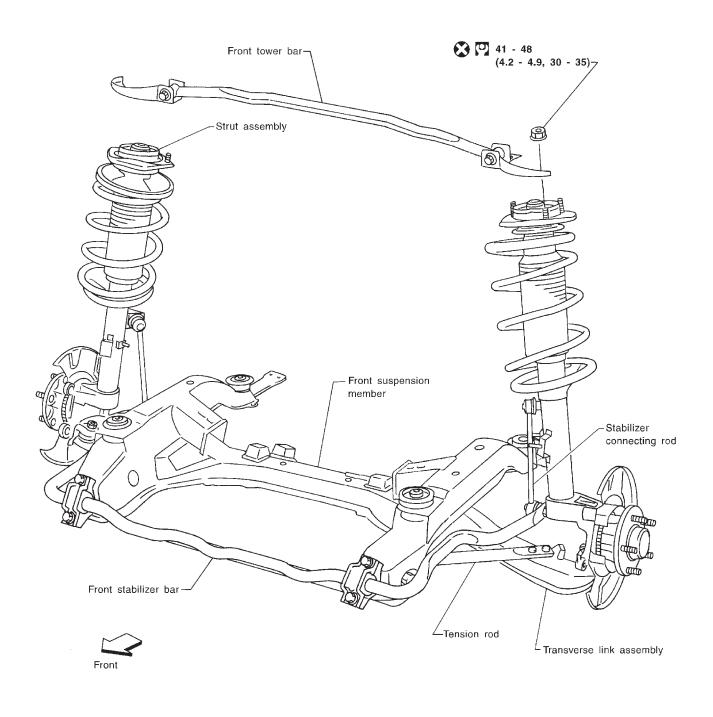
Use the chart below to help you find the cause of the symptom. If necessary, repair or replace these parts.

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Reference	page		FA-6, 17	FA-18	Ι	Ι	1	FA-17	FA-9	FA-22	FA-14	FA-10	I	Ι	Ι	Ι	Ι	Ι			Refer to FRONT AXLE AND FRONT SUSPENSION in this chart.			Refer to ROAD WHEEL in this chart.				LC
																					KLE AND		Refer to TIRES in this chart.	HEEL in .				EC
																			NVH in PD section	NVH in PD section	ONT A)	NVH in RA section	RES in t	AD WH	NVH in RA section	NVH in BR section	NVH in ST section	FE
																			in PD	in PD	to FR	in RA	to TIF	to RC	in RA	in BR	in ST	
																			ΗΛΝ	ΗΛΝ	Refer	ΗΛΝ	Refer	Refer	ΗΛΝ	ΗΛΝ	ΗΛΝ	AT
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5051 ECT	LUTARIO		tion, loc	deform	iting de	۵		eness	alignme	gue	amage			sure		amage		0	IAFT		ND FRO	D REAF						BR
			Improper installation, looseness	Shock absorber deformation, damage or deflection	Bushing or mounting deterioration	Parts interference	Spring fatigue	Suspension looseness	Incorrect wheel alignment	Stabilizer bar fatigue	Wheel bearing damage	Out-of-round	nce	Incorrect air pressure	Uneven tire wear	Deformation or damage	Non-uniformity	Incorrect tire size	PROPELLER SHAFT	DIFFERENTIAL	FRONT AXLE AND FRONT SUSPENSION	REAR AXLE AND REAR SUSPENSION		ROAD WHEEL	DRIVE SHAFT	S	RING	ST
			Improp	Shock	Bushir	Parts i	Spring	Suspe	Incorre	Stabili	Wheel	Out-of	Imbalance	Incorre	Uneve	Deforn	Non-ui	Incorre	PROP	DIFFE	FRON	REAR	TIRES	ROAD	DRIVE	BRAKES	STEERING	RS
		Noise	Х	Х	Х	Х	Х	Х											Х	Х		Х	Х	Х	Х	Х	Х	110
	FRONT	Shake	X	X	Х	Х		Х											Х			X	Х	Х		Х	X	
	AXLE AND	Vibration	Х	Х	Х	Х	Х												Х			Х	Х		Х		X	BT
	FRONT SUSPEN-	Shimmy	X		Х	Х			Х													X		X		X	X	
	SION	Judder Poor quality ride or handling	X X	X X	X X	х	x		x	x	x											X X	X X			X	X	HA
		Noise	x									Х	Х	Х	Х	Х	Х		Х	Х	Х	X		Х	Х	Х	x	
		Shake	X									X	X	X	X	Х		Х	X		X	X		X	X	X	X	EL
Symptom		Vibration	1	1										Х				Х	X		X	X			X		X	کت
	TIRES	Shimmy	X									Х	Х	Х	Х	Х	Х	Х			Х	X		Х		Х	X	
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		Poor quality ride or handling	x									х	х	х	х	х		х			х	x		х				
		Noise	Х									Х	Х			Х			Х	Х	Х	Х			Х	Х	Х	
	ROAD	Shake	X	<u> </u>								Х	Х			Х			Х		Х	X	Х		Х	X	X	
	WHEEL	Shimmy, judder	Х	<u> </u>								Х	Х			Х					Х	X	Х			Х	X	
		Poor quality ride or handling	x									х	х			Х					х	x	х					

X: Applicable

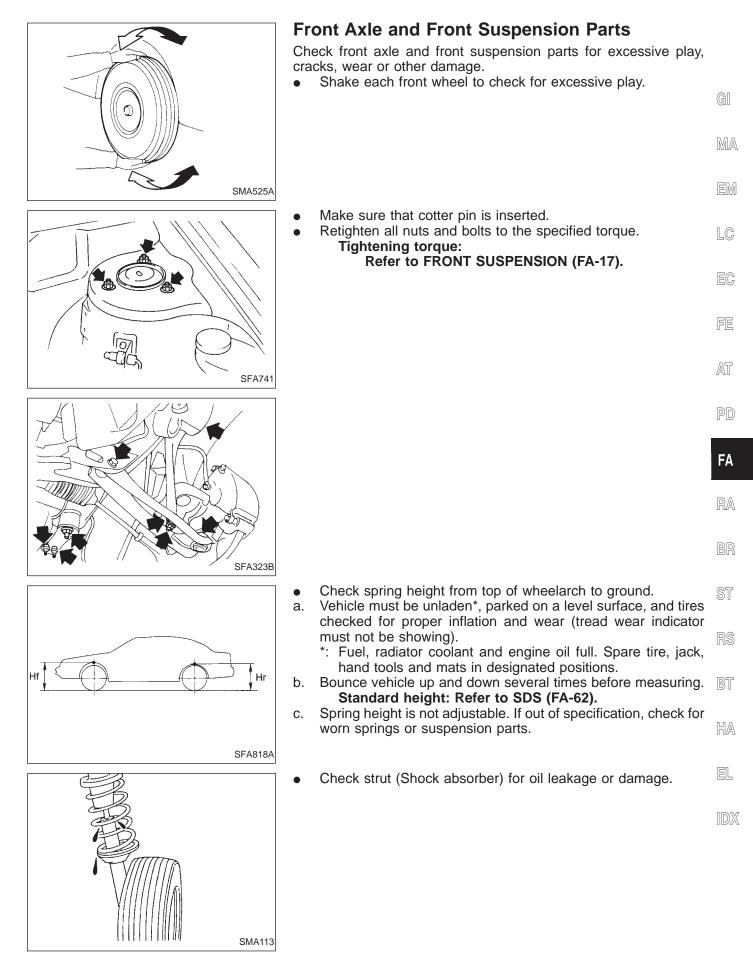


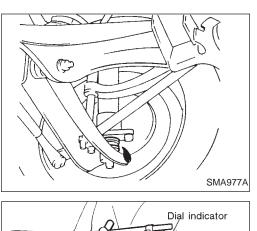
SEC. 400•401



🕐 : N•m (kg-m, ft-lb)

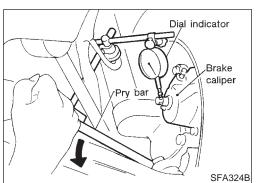






Front Axle and Front Suspension Parts (Cont'd)

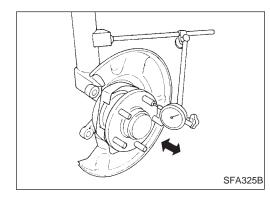
 Check suspension ball joint for grease leakage and ball joint dust cover for cracks or other damage. If ball joint dust cover is cracked or damaged, replace transverse link.



- Check suspension ball joint end play.
- a. Jack up front of vehicle and set the stands.
- b. Clamp dial indicator onto transverse link and place indicator tip on lower edge of brake caliper.
- c. Make sure front wheels are straight and brake pedal is depressed.
- d. Place a pry bar between transverse link and inner rim of road wheel.
- e. While raising and releasing pry bar, observe maximum dial indicator value.

Vertical end play: 0 mm (0 in)

If ball joint vertical end play exists, remove transverse link and recheck the ball joint. Refer to FA-23.



Front Wheel Bearing

Check that wheel bearings operate smoothly, as well as axial end play and grease leakage.

- Axial end play limit: 0.05 mm (0.0020 in) or less
- If out of specification or wheel bearing does not turn smoothly, replace wheel bearing assembly. Refer to FRONT AXLE (FA-13).

FA-8

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(6)

4

Dunning-

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(8)

Remove

Remove

 $(\mathbf{1})$ (4)

6 to 9

X SFA894AA

5

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For 5 hub bolts

Wheel

D

Hub bolt

V

3



Front Wheel Alignment CAMBER, CASTER AND KINGPIN INCLINATION Camber, caster and kingpin inclination are preset at factory and cannot be adjusted. GI 1. Set vehicle on turning radius gauge. MA EM 2. Mount Tool as follows. **Tool number:** LC KV991040S0 ((5) KV99104010 ① to ⑤ KV99104020 (6) KV99104030 (7) KV99104040 (8) KV99104050 (9) FE Select adapter which corresponds with wheel or hub shape a. from four types (6) to (9). M Screw selected adapter in until it contacts plate ①. AT b. PD FA 9 RA BR SFA637B Remove wheel nuts. c. BT HA For 4 hub bolts SFA893A Install guide bolts (2) to where wheel nuts were removed and \mathbb{E} d. 3 tighten them by hand. (2) Install plate and adapter assembly to guide bolts (2). e.

- Install springs (a) onto guide bolts (2). Then tighten nuts $\mathbb{D}^{\mathbb{X}}$ f.
 - (3) evenly until a little before springs (4) are completely compressed.
- Install center plate (5). g.
- h. Mount wheel alignment gauge on attachment plate.

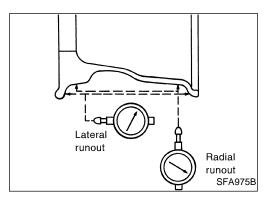
FA-9



Front Wheel Alignment (Cont'd)

Before checking front wheel alignment, be sure to make a preliminary inspection (Unladen*).

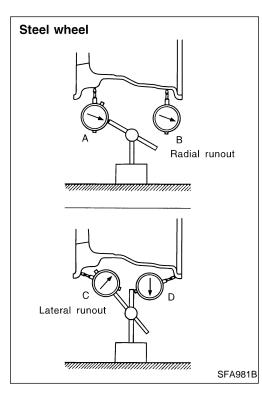
*: Fuel, radiator coolant and engine oil full. Spare tire, jack, hand tools and mats in designated positions.



PRELIMINARY INSPECTION

Aluminum wheel

- 1. Check tires for wear and improper inflation.
- 2. Check wheels for deformation, cracks and other damage. If deformed, remove wheel and check wheel runout.
- a. Remove tire from aluminum wheel and mount on a tire balance machine.
- b. Set dial indicator as shown in the illustration.
 Wheel runout (Dial indicator value): Refer to SDS.
- 3. Check front wheel bearings for looseness.
- 4. Check front suspension for looseness.
- 5. Check steering linkage for looseness.
- 6. Check that front shock absorbers work properly.
- 7. Check vehicle posture (Unladen).



Steel wheel

- 1. Check tires for wear and improper inflation.
- 2. Check wheels for deformation, cracks and other damage. If deformed, remove wheel and check wheel runout.
- a. Remove tire from steel wheel and mount wheel on a tire balance machine.
- b. Set two dial indicators as shown in the illustration.
- c. Set each dial indicator to 0.
- d. Rotate wheel and check dial indicators at several points around the circumference of the wheel.
- e. Calculate runout at each point as shown below.

Radial runout = (A + B)/2

Lateral runout = (C + D)/2

f. Select maximum positive runout value and the maximum negative value.

Add the two values to determine total runout.

In case a positive or negative value is not available, use the maximum value (negative or positive) for total runout.

If the total runout value exceeds the limit, replace steel wheel. Wheel runout:

Refer to SDS.

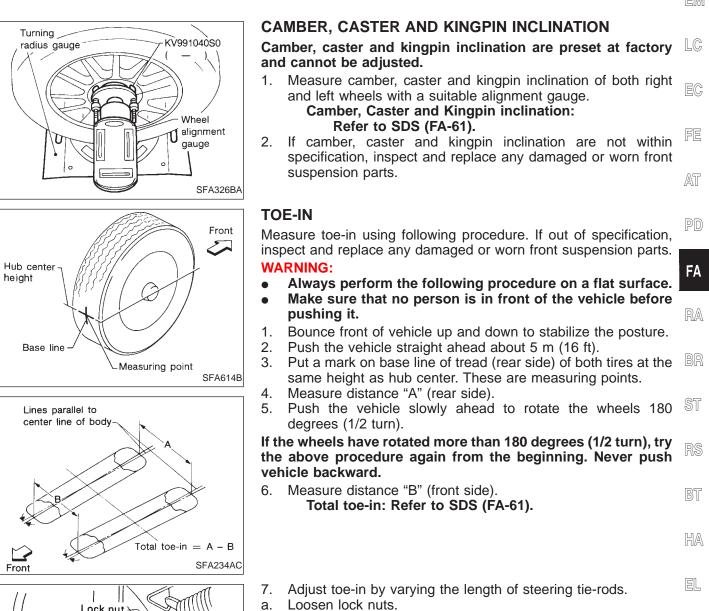
- Check front wheel bearings for looseness.
- 4. Check front suspension for looseness.
- 5. Check steering linkage for looseness.

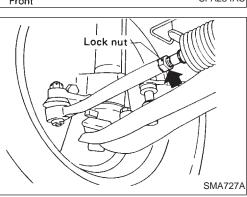
3.

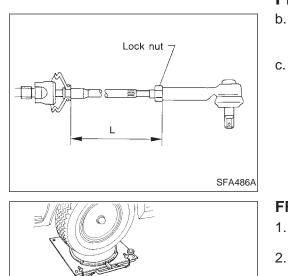
Front Wheel Alignment (Cont'd)

- 6. Check that front shock absorbers work properly.
- 7. Check vehicle posture (Unladen).

MA







B | A

↓ Front Angle A:

Inside tire on turn Angle B:

Outside tire on turn

SFA439BA

AB

Front Wheel Alignment (Cont'd)

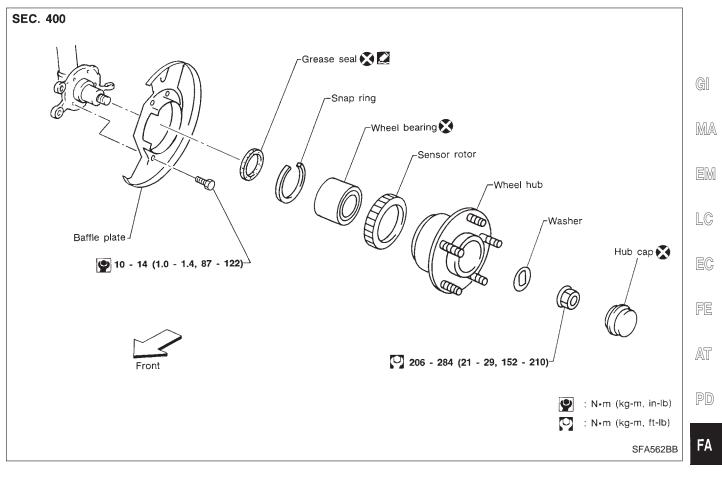
- b. Adjust toe-in by screwing tie-rods in and out. Standard length "L": Refer to SDS in ST section.
 - Tighten lock nuts to specified torque.
 - Lock nut tightening torque: Refer to POWER STEERING GEAR AND LINKAGE in ST section.

FRONT WHEEL TURNING ANGLE

- 1. Set wheels in straight-ahead position. Then, move vehicle forward until front wheels rest on turning radius gauge properly.
- 2. Rotate steering wheel all the way right and left; measure turning angle.

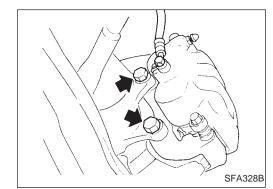
Wheel turning angle (Full turn): Refer to SDS (FA-61).

FRONT AXLE



RA

BR



Wheel Hub and Knuckle REMOVAL

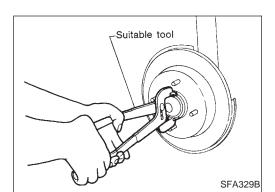
- Remove brake caliper assembly and rotor.
 CAUTION:
- Brake hose need not be disconnected from brake caliper.
 Be careful not to depress brake pedal, or piston will pop out. Do not pull or twist brake hose.
- Before removing the front axle assembly, disconnect the ABS wheel sensor from the assembly. Then, move it away from the front axle assembly area. Failure to do so may result in damaging the sensor wires and the sensor will become inoperative.

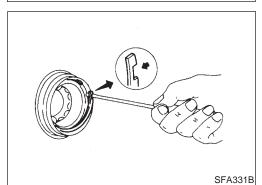
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Wheel Hub and Knuckle (Cont'd)

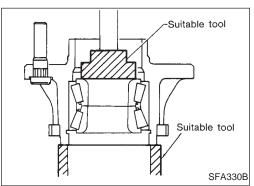
• Remove wheel hub from spindle.





Remove grease seal.Remove snap ring.

• Press out bearing and race as a set.



INSPECTION

Wheel bearing

Check wheel bearing to see that it rolls freely and is free from noise, crack, pitting, or wear, and replace if damaged.

Wheel hub

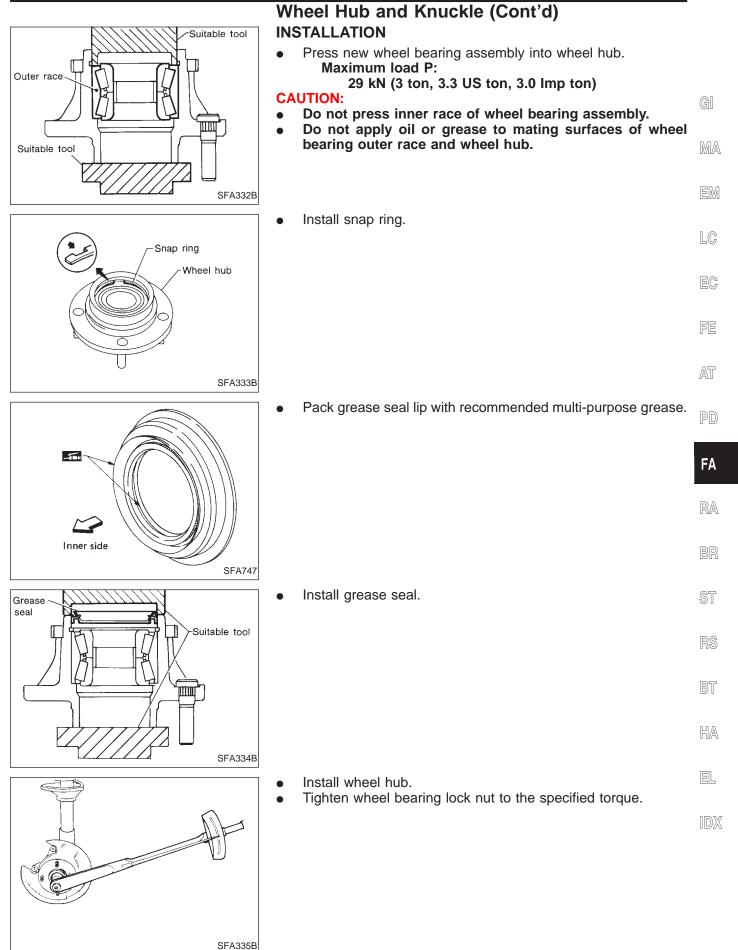
Check wheel hub for crack by a magnetic exploration or dyeing test, and replace if cracked.

Knuckle spindle

Check knuckle spindle for deformation, tapping mark, or cracks (by magnetic or dyeing test) and replace if damaged.

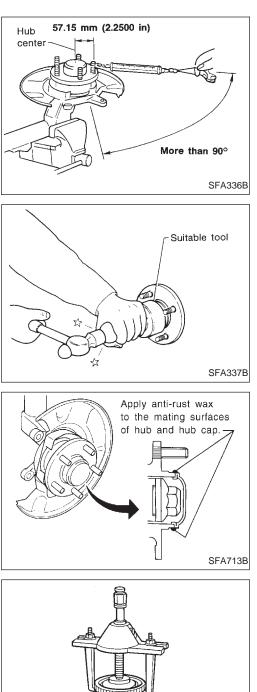


FRONT AXLE









Wheel Hub and Knuckle (Cont'd)

- Turn wheel hub several times in both directions to seat wheel bearing correctly.
- Attach spring balance to wheel hub bolt (as shown at left) and pull it at a speed of 10 rpm to measure rotation torque. **Rotation torque:**

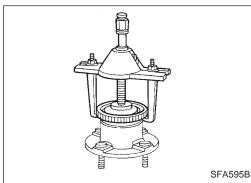
0.25 - 2.11 N m (2.5 - 21.5 kg-cm, 2.2 - 18.7 in-lb) Spring balance indication:

3.9 - 37.2 N (0.4 - 3.8 kg, 0.9 - 8.4 lb) If bearing preload does not meet the specification, replace wheel bearing assembly.

Clinch lock nut using standard screwdriver and install hub cap using a suitable tool.

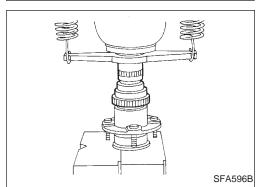
Do not reuse hub cap. When installing, replace it with a new one.

Apply anti-rust wax to the mating surfaces of hub and hub cap.



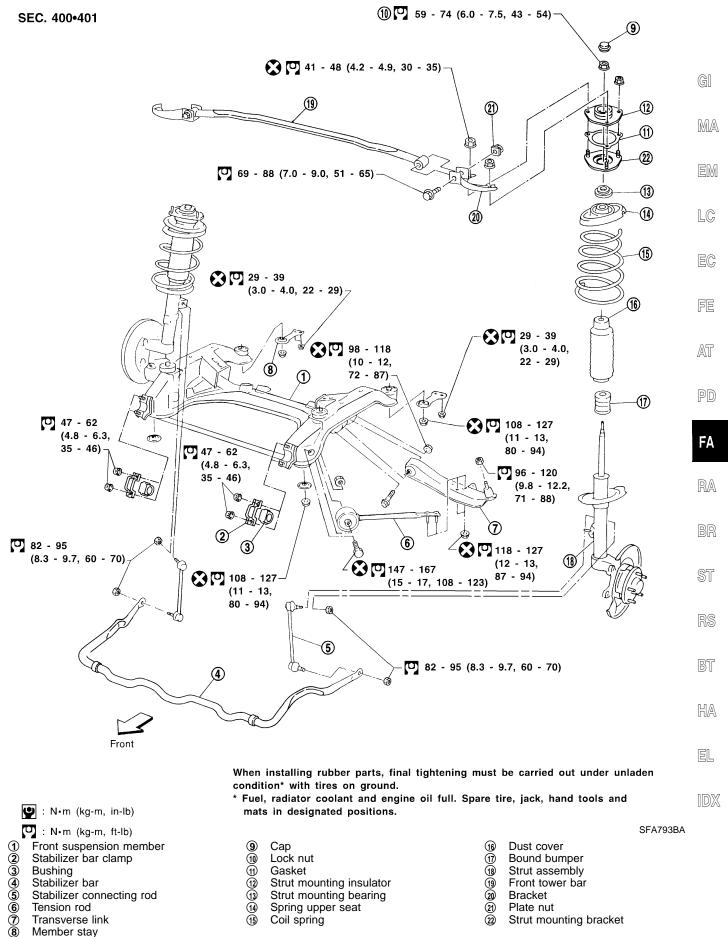
ABS Sensor Rotor REMOVAL

Remove ABS sensor rotor.



INSTALLATION Press-fit ABS sensor rotor.





- Stabilizer bar clamp Bushing
- Stabilizer bar
- Stabilizer connecting rod
- Tension rod
- Transverse link
- Member stay

- 17 Bound bumper
- <u>(18</u> Strut assembly
- (19) 20 Front tower bar
- Bracket
- 21 Plate nut
- 22 Strut mounting bracket

FA-17

Strut mounting insulator

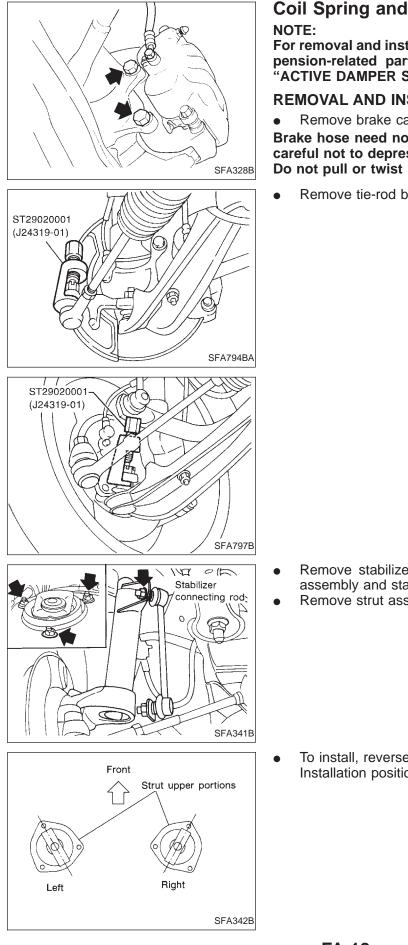
Strut mounting bearing

Spring upper seat

Gasket

Coil spring

(15)



Coil Spring and Strut Assembly

For removal and installation procedures of active damper suspension-related parts, refer to "Removal and Installation", "ACTIVE DAMPER SUSPENSION", FA-28.

REMOVAL AND INSTALLATION

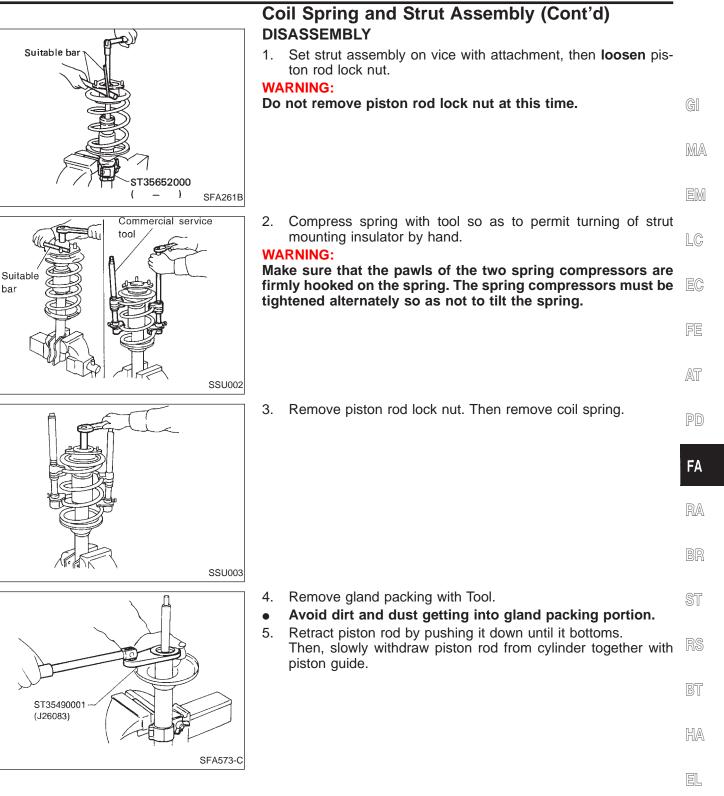
Remove brake caliper assembly and rotor. Brake hose need not be disconnected from brake caliper. Be careful not to depress brake pedal, or piston will pop out. Do not pull or twist brake hose.

Remove tie-rod ball joint and lower ball joint with Tool.

- Remove stabilizer connecting rod upper nut, separate strut assembly and stabilizer connecting rod.
- Remove strut assembly upper nuts.

To install, reverse above removal procedures. Installation position of upper end of strut is shown at left.

FRONT SUSPENSION



[DX



Coil Spring and Strut Assembly (Cont'd) INSPECTION

Wash all parts, except for nonmetallic parts, clean with suitable solvent and dry with compressed air.

Blow dirt and dust off of nonmetallic parts using compressed air.

Strut assembly

 Oil oozing out around gland packing does not need strut replacement.
 If oil leakage is evident on spring seat, check piston rod gland packing and O-ring.

If oil leakage occurs on welded portion of outer strut casing, replace strut assembly.

• If shock absorber itself is malfunctioning, replace as shock absorber kit.

Gland packing

Check gland packing for oil leakage. Replace gland packing if necessary.

Strut mounting insulator

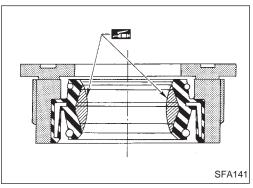
Check cemented rubber-to-metal portion for melting or cracks. Check rubber parts for deterioration. Replace if necessary.

Thrust seat

Check for cracks, deformation or other damage. Replace if necessary.

Coil spring

Check for cracks, deformation or other damage. Replace if necessary.



SFA141

ASSEMBLY

• Lubricate sealing lip of gland packing.

Install gland packing.

Cover piston rod with tape so as not to damage oil sealing lip.

SFA574

FRONT SUSPENSION



GI

MA

EM

LC

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PD

FA

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BR

ST

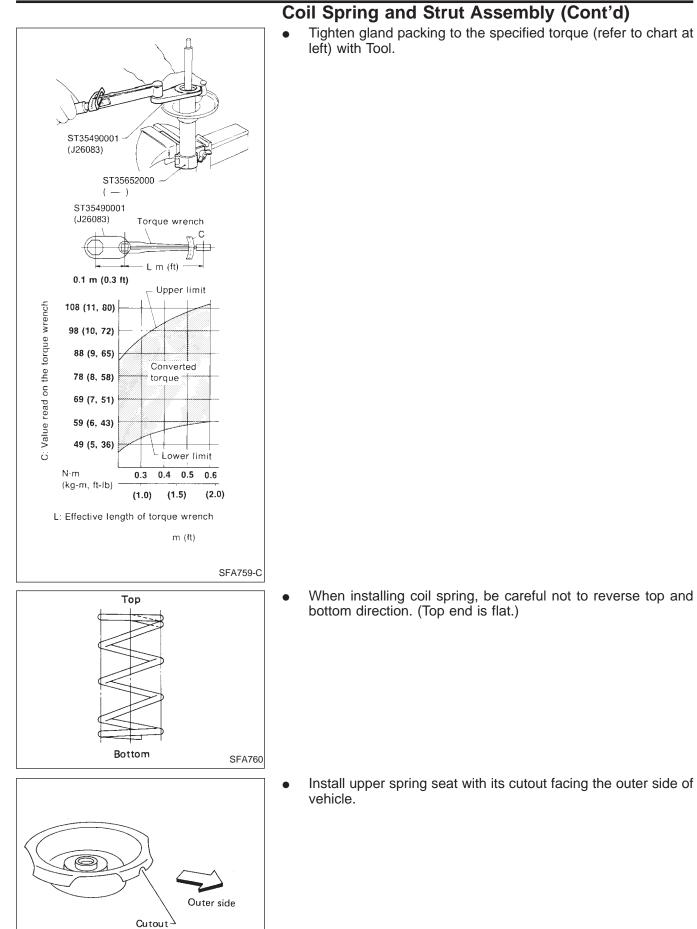
RS

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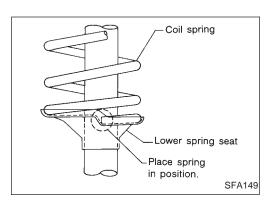


SFA664A

FA-21

Coil Spring and Strut Assembly (Cont'd)





Coonnecting rod

Stabilizer bar

After placing spring in position on lower spring seat, release spring compressor gradually.

Tension Rod and Stabilizer Bar REMOVAL AND INSTALLATION

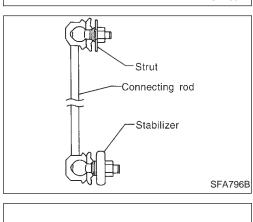
- Remove tension rod and stabilizer bar.
- Prevent stabilizer connecting rod from turning by inserting hex wrench into end of ball stud, then remove nut.
- Press. Press. Drift Drift SFA837A

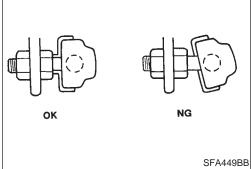
Tension rod

SFA795B

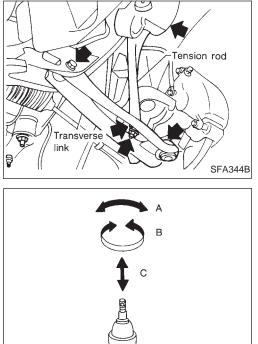
- Place a drift on lower side of tension rod bushing and another on upper side, as shown. Remove tension rod bushing by pressing it out.
- Place arrow mark on bushing facing tension rod before installing bushing.

Install stabilizer bar with ball joint socket properly placed.









Transverse Link Assembly

REMOVAL AND INSTALLATION

- Separate suspension ball joint from knuckle arm. •
- Remove tension rod and transverse link assembly. •

MA

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• • SFA858A

INSPECTION

- Check tension rod, stabilizer bar and transverse link for $\mathbb{L}\mathbb{G}$ damage, cracks, deformation; replace transverse link assembly if necessary.
- Check rubber bushing for damage, cracks and deformation; replace tension rod or transverse link assembly if necessary.
- Check ball joint for excessive play. Replace transverse link FE assembly if any of the following exists:
 - Ball stud is worn.
 - Joint is hard to swing.
 - Play in axial direction is excessive.

Before checking, turn ball joint at least 10 revolutions so that ball joint is properly broken in. PD

- Swinging force: Refer to SDS (FA-62). **Turning torque:** Refer to SDS (FA-62). Vertical end play: Refer to SDS (FA-62).
- RA Check dust cover for damage. Replace it and cover clamp if necessary.

BR

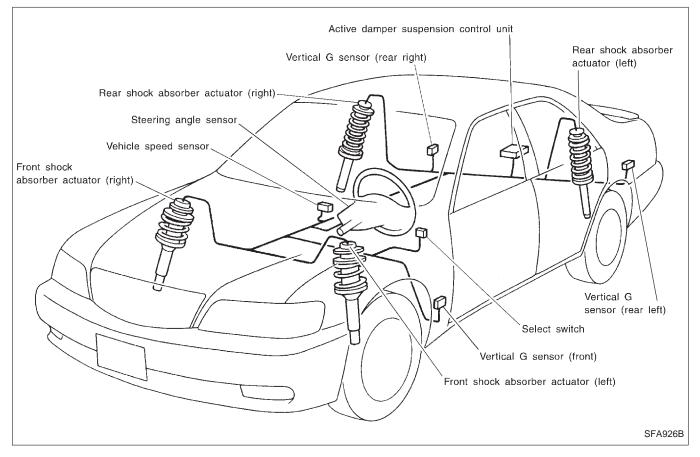
FA

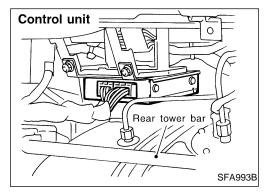
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System Components





Steering angle sensor

Component Description CONTROL UNIT

The control unit calculates the direction and the speed of the vehicle based on input signals from each sensor, and controls actuators (step motors) for optimum damping force of shock absorbers. In case of the trouble in the electric system, the control unit controls actuators (step motors) for constant damping force according to signals stored in control unit.

STEERING ANGLE SENSOR

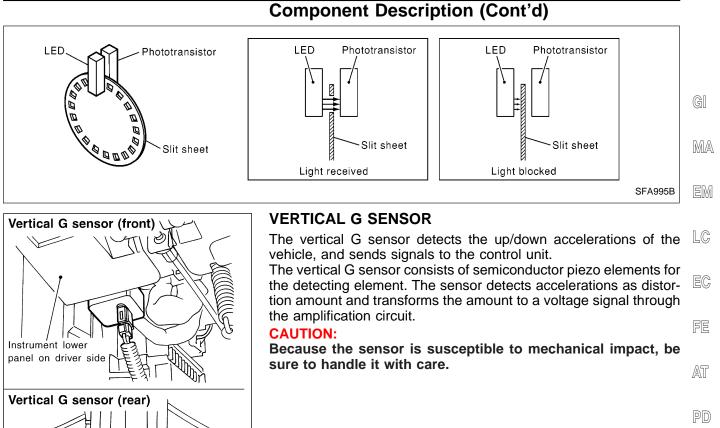
Three optical, non-contact type sensors are used to send signals of the steering direction, neutral position, and lock angle to the control unit.

Steering angle sensors consist of LEDs, phototransistors which transform light to electric signals, and slit sheets which rotate with the steering wheel. The sensors receive light through slit sheets which rotate and shade light, turning ON/OFF the phototransistors.



ACTIVE DAMPER SUSPENSION

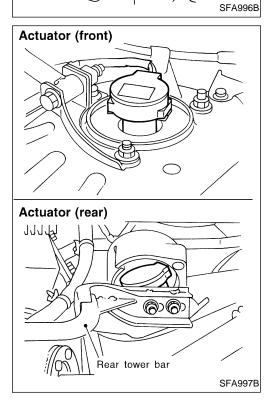
Component Description (Cont'd)





BR

ST



SHOCK ABSORBER ACTUATOR

Shock absorber actuators are installed on the upper part of shock absorbers to control the damping force of shock absorbers by out-RS put signals from the control unit. The motor operating angle is about 70°. The shock absorber actuator instantly controls 140 patterns of damping force.

HA

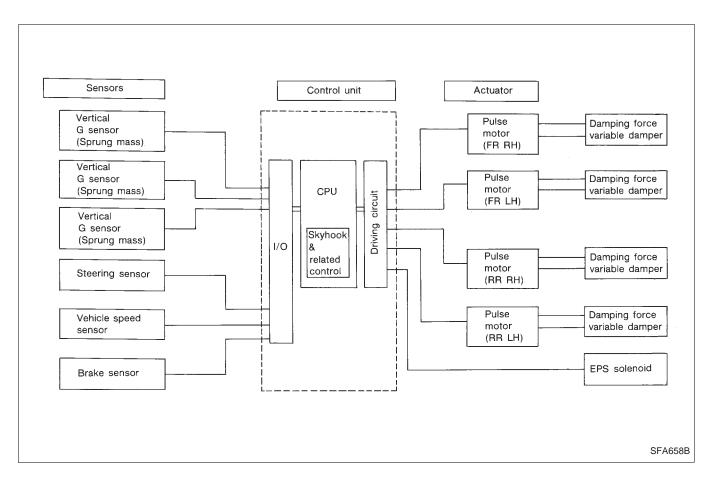
BT

EL

IDX

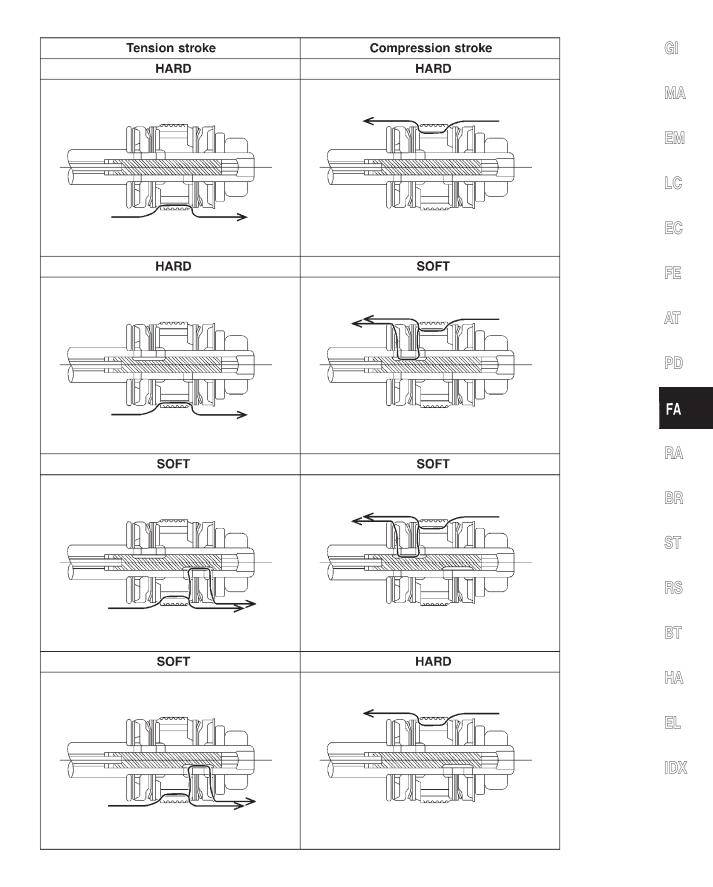


Active Damper Suspension Configuration



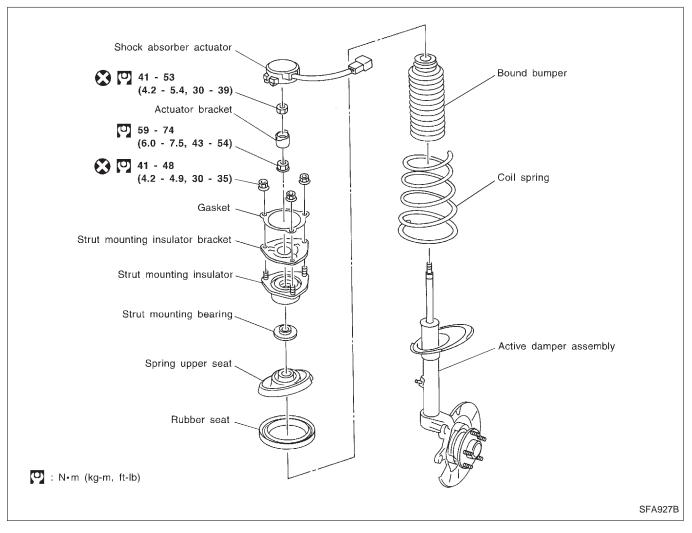


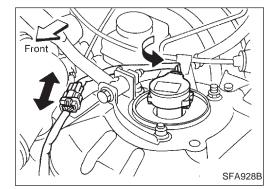
Active Damper



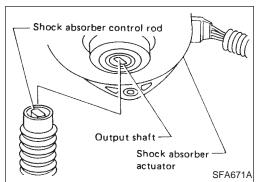


Removal and Installation





- Disconnect sub-harness connector.
 - Turn shock absorber actuator counterclockwise, then remove from bracket.



- Before installing actuator, ensure shock absorber control rod is aligned with actuator output shaft. Otherwise, actuator may be damaged.
- Refer to FRONT SUSPENSION for other procedures.

INSPECTION

 Replace shock absorber assembly if it is damaged.
 Refer to FRONT SUSPENSION — Coil Spring and Strut Assembly (FA-18).

FA-28



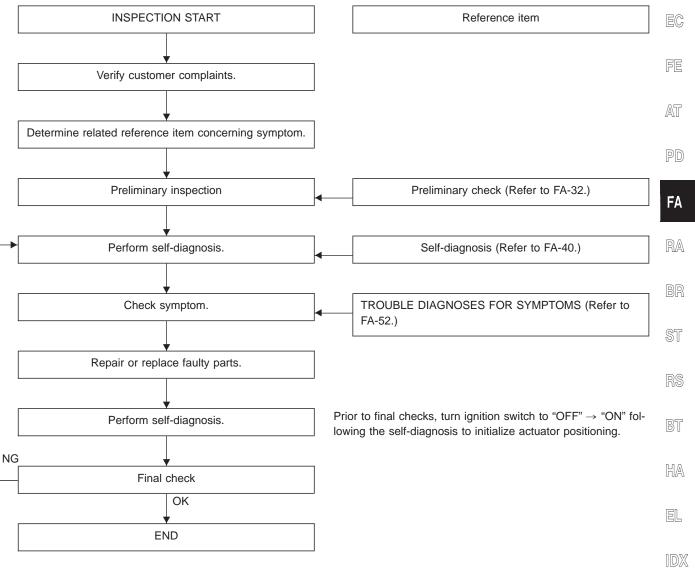
LC

How to Perform Trouble Diagnoses for Quick and Accurate Repair

INTRODUCTION

- Before troubleshooting, verify customer complaints concerning his vehicle.
- If a vehicle problem is hard to reproduce, harnesses, harness connectors and/or terminals may often be faulty. Hold and shake these parts by hand to make sure they are securely connected.
- When using a circuit tester to measure voltage or resistance of each circuit, be careful not to expand connector terminals unnecessarily.

WORK FLOW





Symptom Chart

PRC	OCEDURE			NOS SEL	SES F	GNO	-	NOS	UBLE SES F IPTOI		G-
SYM	IPTOM			Procedure 1	Procedure 2	ocedure 3	Procedure 4	ocedure 5	Procedure 6	ocedure 7	Procedure 8
	Self-diagnosis code No.	Diagnosed part	CONSULT-II indication	Diagnostic Pr	Diagnostic Pr	Diagnostic Procedure	Diagnostic Pr	Diagnostic Procedure	Diagnostic Pr	Diagnostic Procedure	Diagnostic Pr
	11	Vehicle speed sensor	VHCL SPEED SE [km/h] or [mph]	0							
esults	12	Steering angle sensor (Steering angle signal)	STEERING ANG [°]		0						
nostic r	13	Steering angle sensor (Steering neutral signal)	NEUTRAL SIG [ON-OFF]		0						
Self-diagnostic results	14	Stop lamp switch	DATA MONITOR mode "STOP LAMP SW" Brake pedal depressed: ON Brake pedal release: OFF			0					
	22	Vertical G sensor front	VERTI G SE FL [G]				0				
	23	Vertical G sensor rear right side	VERTI G SE RR [G]				0				
	24	Vertical G sensor rear left side	VERTI G SE RL [G]				0				
Indic	cator lamp in me	ter cluster does not illuminat	ie.					0			
Hard	d or soft (riding c	comfort) feel.							0		
Hea	vy steering opera	ation during stationary turns.								0	
Ligh	t steering during	high-speed operation.									0



Fail-safe Remarks

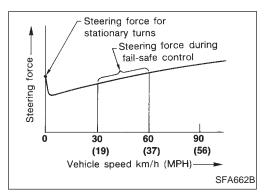
FAIL-SAFE FUNCTION (Active damper suspension)

The active damper suspension electronically controls the shock absorber dampening force. If, for some reason, the dampening force falls under any of the conditions listed in the "Fail-safe items" table below, the fail-safe system will activate to maintain a constant level of shock absorber dampening force. If symptoms (such as unstable steering, unpleasant riding comfort, etc.) are pointed out, check and correct the faulty part or area using the diagnostic procedure outlined under "Diagnostic Procedure 6 (Hard or soft feel)".



The electric control power steering (EPS) electrically controls the solenoid valve in response to vehicle speeds. If any of the conditions listed in the table below are encountered, the fail-safe system will activate so that a constant level of steering force is maintained during high-speed operation. If abnormal steering force is indicated, check and correct the problem using the diagnostic procedure outlined under "Diagnostic Procedure 7 (Heavy steering operation during stationary turns)". Refer to FA-57.

AT

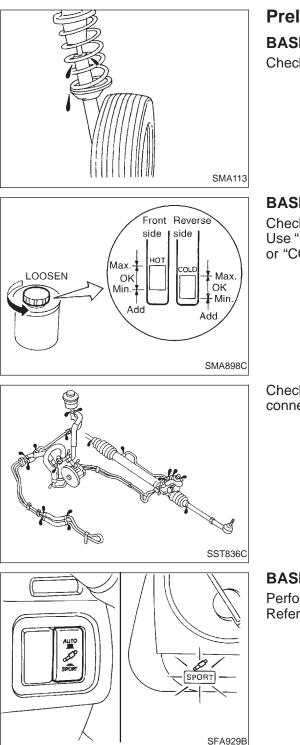


Fail-safe items

Item	Fail-safe input conditions	Fail-safe cancel condi- tions	Operation during fail-safe
Vehicle speed sensor	 Vehicle speed signal cannot be entered for more than 10 seconds when the vehicle is running with the engine revolution greater than 1,500 rpm. Vehicle speed signal changes from a value of greater than 30 km/h (19 MPH) to a value of less than 2 km/h (1 MPH) within 1.4 seconds. 	A signal corresponding to a vehicle speed of greater than 2 km/h (1 MPH) is entered.	 Shock absorber dampening force is maintained at a preset value. Power steering control current is maintained at approximately 0.18A.
Steering angle sensor	A steering signal of greater than 1° does not change for more than 180 seconds when vehicle speed is greater than 60 km/h (37 MPH).	A steering signal of greater than 1° is entered.	Shock absorber dampen- ing force is maintained at a preset value.
Steering angle (neutral) signal	 Steering neutral signal is not entered ("ON") at all while vehicle is being driven a distance of more than 10 km (6 miles). Steering neutral signal is not entered ("ON") at all when steering wheel is turned at least 360° in either direction. Steering neutral signal is entered ("ON") only while steering wheel is being turned at least 50° in either direction. 	More than one ON-OFF signal are entered.	Shock absorber dampen- ing force is maintained at a preset value.
Vertical G sensor	 Vertical G sensor signal corresponding to a voltage of greater than 4.5 volts does not change for 2 seconds. Vertical G sensor signal corresponding to a voltage of less than 0.5 volts does not change for 2 seconds. 	Vertical G sensor signal corresponding to a volt- age of greater than 1 volt or less than 4 volts.	When any of the vertical G sensors are deter- mined to be faulty, shock absorber dampening force is maintained at a preset value.
Stop lamp switch	Fail-safe system does not process data. Faulty area is displayed when self-diagnosis is perf	ormed.	

NOTE: Even after the fail-safe function is canceled, the fail-safe processed history is retained in the control unit memory.





Preliminary Check

BASIC INSPECTION 1

Check shock absorber for oil leakage or other damage.

BASIC INSPECTION 2

Check fluid level in reservoir tank.

Use "HOT" range at fluid temperatures of 50 to 80°C (122 to 176°F) or "COLD" range at fluid temperatures of 0 to 30°C (32 to 86°F).

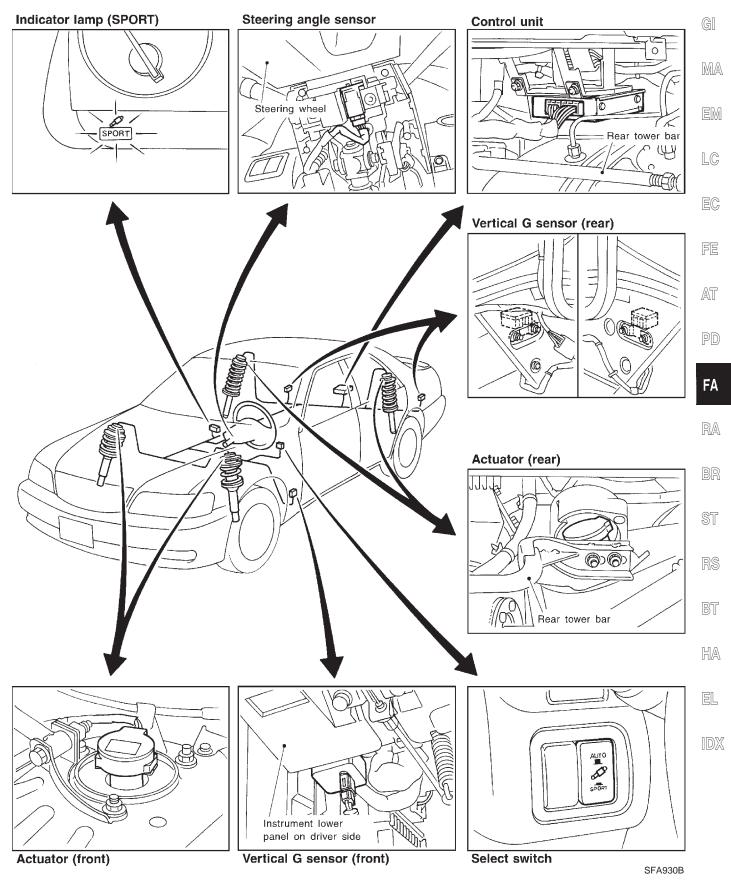
Check lines for improper attachment, leaks, cracks, damage, loose connections, chafing and deterioration.

BASIC INSPECTION 3

Perform self-diagnosis. Refer to "Self-diagnosis", FA-40.



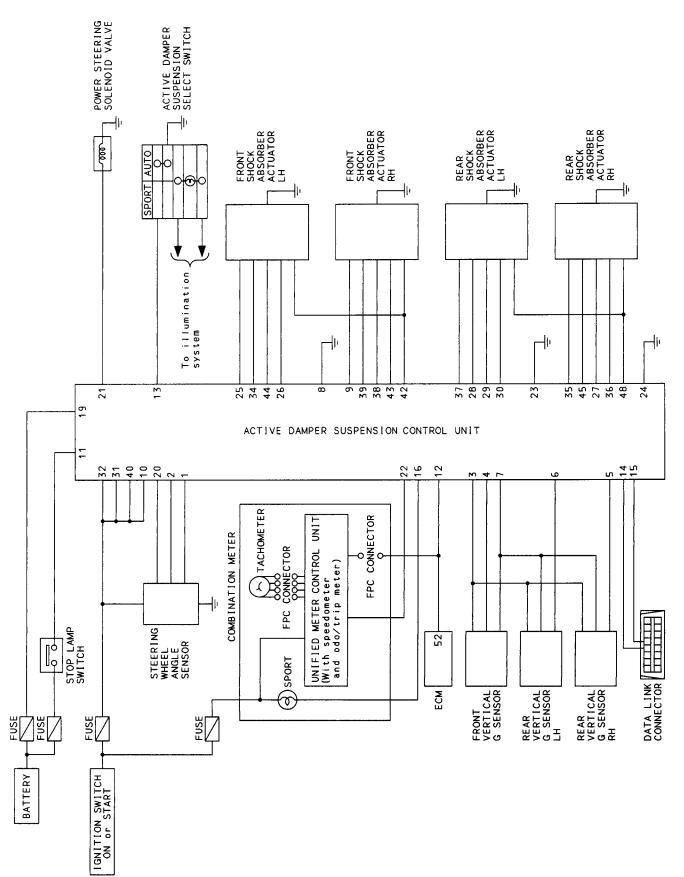
Component Parts and Harness Connector Locations



FA-33

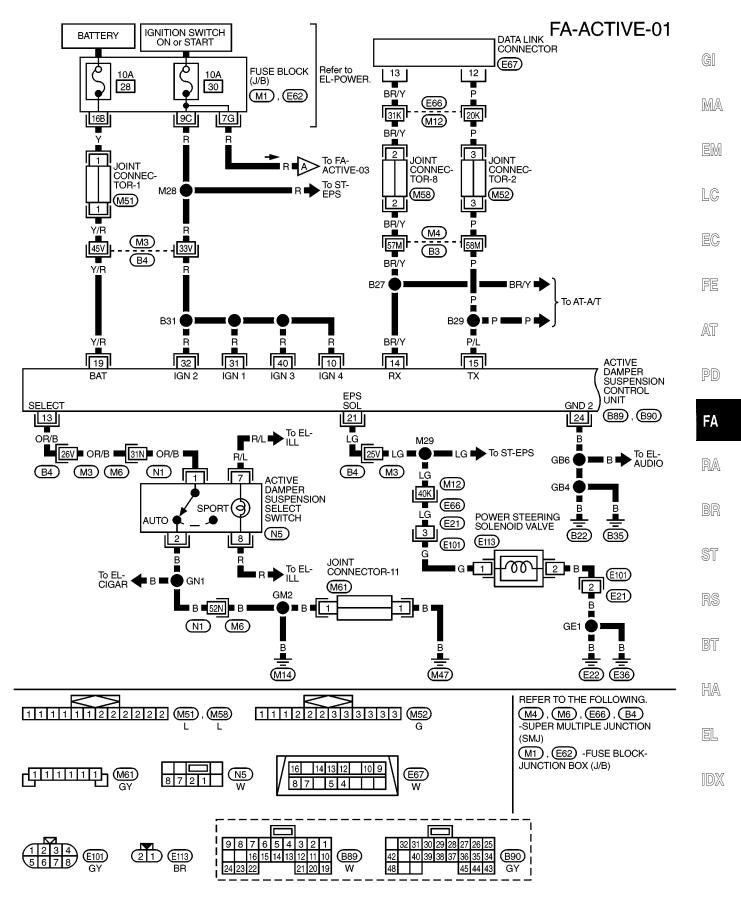






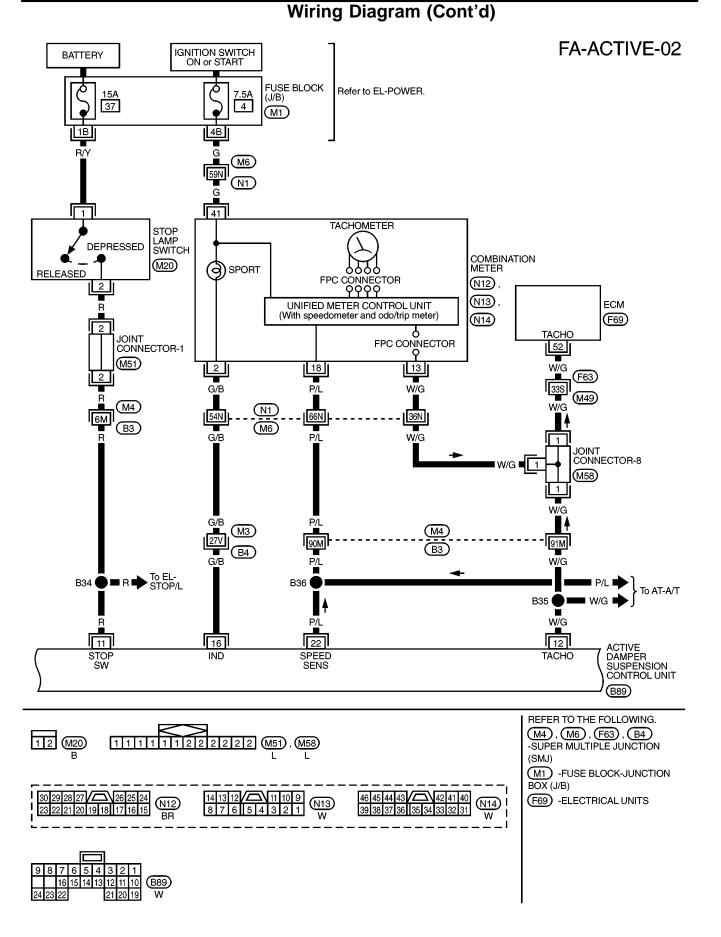


Wiring Diagram



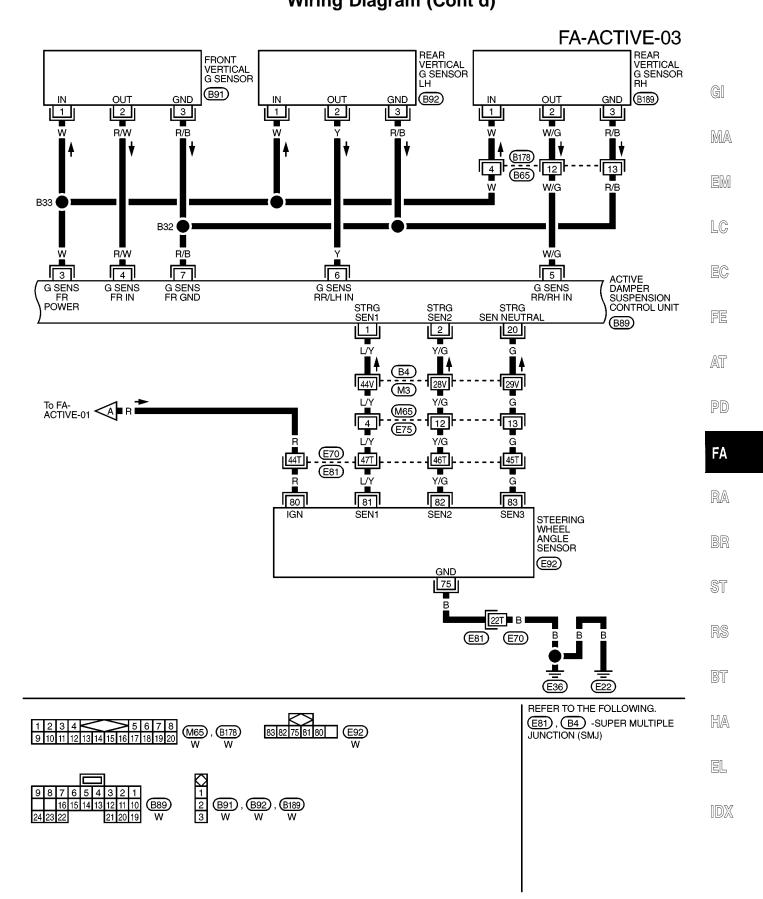


TROUBLE DIAGNOSES



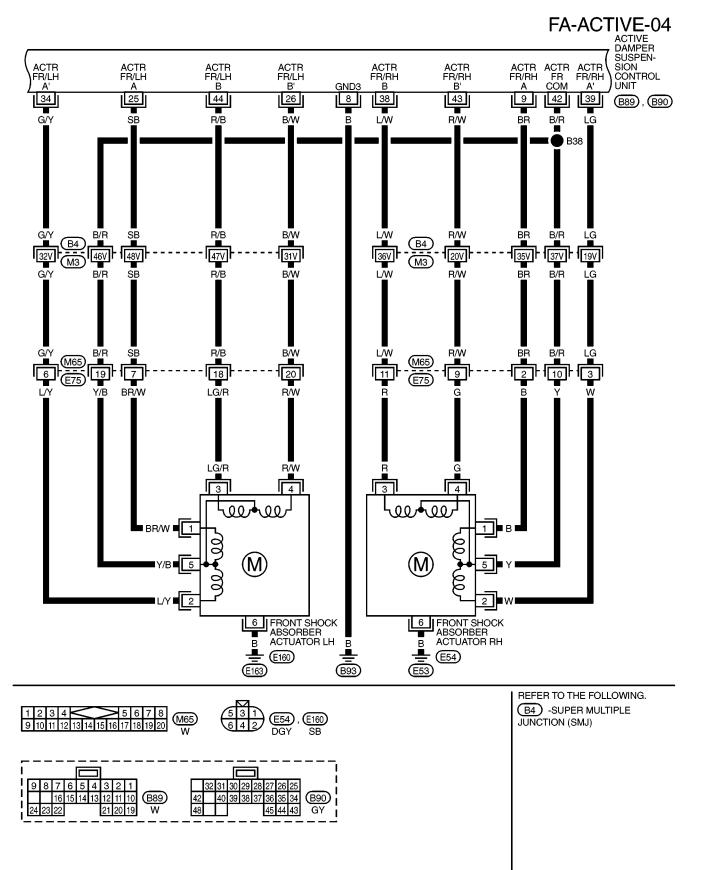


TROUBLE DIAGNOSES Wiring Diagram (Cont'd)





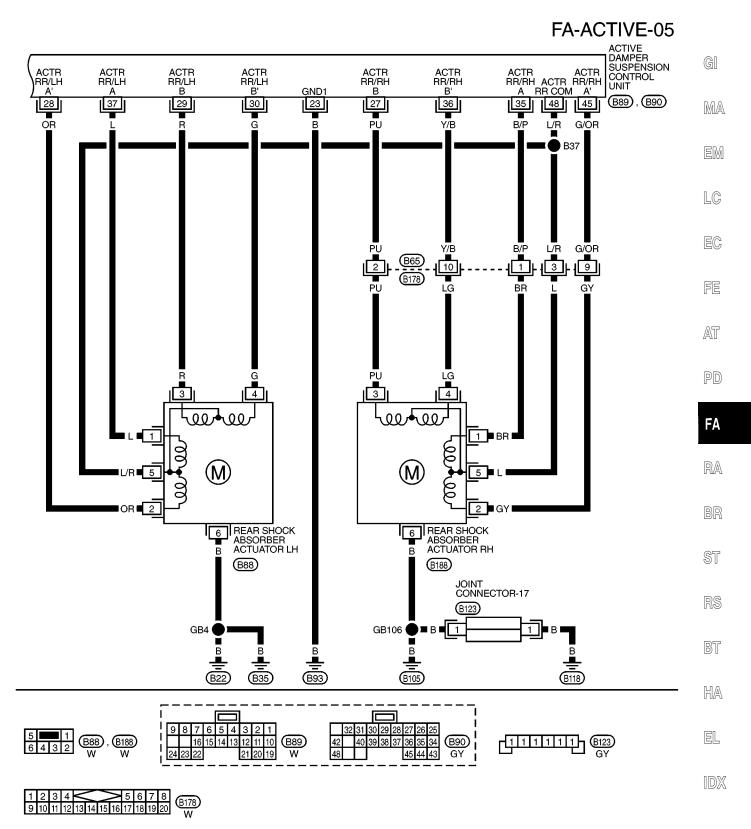
TROUBLE DIAGNOSES Wiring Diagram (Cont'd)





TROUBLE DIAGNOSES Wiring Diagram (Cont'd)

LHD MODELS





Self-diagnoses

FUNCTION

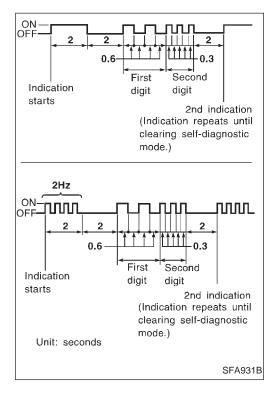
The self-diagnosis system can be used without using CONSULT-II. With this system, both self-diagnostic history and fail-safe history are indicated by the SPORT indicator lamp.

SELF-DIAGNOSTIC PROCEDURE

- 1. Turn ignition switch to "OFF".
- 2. Start the engine.
- 3. Quickly switch the active damper suspension select switch from "SPORT" to "AUTO", and vice versa, at least 5 times within 10 seconds immediately after the engine has started.

2 or 3 seconds following the above switch operation, the indicator lamp will come on. This is not the indication of self-diagnosis.

- 4. Perform the following procedures to enter the corresponding signals.
- Turn steering wheel 180° in either direction from neutral.
- Depress brake pedal.
- Release brake pedal.
- Move the vehicle at least 5 m (16 ft) forward.



HOW TO READ SELF-DIAGNOSTIC RESULTS (Malfunction codes)

Following the steps listed under the "Self-diagnostic procedure" above, a faulty area or faulty areas, if any, are indicated by a flashing active damper suspension indicator lamp located in the meter cluster.

The indicator lamp flashes to show faulty areas corresponding with No. 11 through 14, then No. 21, 23 and 24, in that order. 2 seconds after all items are indicated, the indicator lamp repeats the flash sequence for all items again.

• When all items are in good order, the indicator lamp flashes at a cycle of 1/4 Hz [ON (2 seconds) and OFF (2 seconds)].

Display mode: First digit "ON" (0.6 seconds) Second digit "ON" (0.3 seconds)

- The upper part of the figure at left shows an example of a faulty area corresponding with No. 23.
- The lower part of the figure at left shows an example of a faulty area (No. 23) which previously fell under the fail-safe history data and is still stored in the current fail-safe data history.

After repairing the faulty area(s), erase the self-diagnostic data stored in memory. [Refer to "HOW TO ERASE SELF-DIAGNOS-TIC RESULTS (Malfunction codes)", FA-41].

Self-diagnoses (Cont'd) MALFUNCTION CODE/SYMPTOM CHART

Code No.	Diagnostic item	
11	Vehicle speed sensor	
12	Steering angle sensor	GI
13	Steering angle (neutral) sensor	
14	Stop lamp switch	MA
22	Vertical G sensor (front)	00000
23	Vertical G sensor (rear right)	FM
24	Vertical G sensor (rear left)	GIVI

HOW TO ERASE SELF-DIAGNOSTIC RESULTS (Malfunction codes)

Disconnecting the self-diagnostic function

Disconnect the self-diagnostic function using one of the following three methods:

- Turn the ignition switch to "OFF".
- Drive the vehicle at speeds greater than 30 km/h (19 MPH).
- Connect CONSULT-II.

Clearing the self-diagnostic memory

Clear self-diagnostic data and fail-safe data stored in memory as $$\operatorname{PD}$$ follows:

• While self-diagnosis is being performed, depress the brake pedal at least 5 times and shift the select switch position at least 5 times. Pedal depression and switch shifting must be done within 10 seconds during self-diagnosis.

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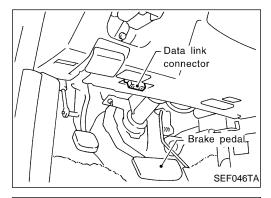
CONSULT-II Inspection Procedure

The troubleshooting system provides four functional modes — selfdiagnosis, data monitor, active test and control unit part number display modes.

Mode type	Description	Mode selection	Display representation
SELF-DIAG RESULTS	Self-diagnosis		
DATA MONITOR	 Helps locate main trouble cause according to a self-diagnostic result. Provides active damper suspension control unit input and output monitoring and print-out function (observation and recording). 	The desired functional mode can easily be	The desired functional
ACTIVE TEST	 Used to precisely locate the main cause for trouble according to the self-diagnostic result obtained in the data monitor mode. Provides operational checks of indicator light and actuator circuits. 	selected by means of touch keys on CON- SULT-II.	mode can easily be shown on the CON- SULT-II display.
ECU PART NUMBER	Active damper control unit part numbers are shown on the CONSULT-II display.		

ECU (Active damper suspension control unit) part number mode

Ignore the ECU part number displayed in the ECU PART NUMBER MODE. Refer to parts catalog to order the ECU.



SELF DIAG RES					
DTC RESULTS	DTC RESULTS TIME				
VEHICLE SPEED SEN	xxx				
		SFA98			

SELF-DIAGNOSIS PROCEDURE

1. Connect CONSULT-II to data link connector and start the engine.

- 2. Touch "START", "ACT D/SUS" and "SELF-DIAG RESULTS".
- 1) When a faulty item is displayed, record the item.
- 2) Touch "ERASE".



SELF DIAG RES	ULTS	
DTC RESULTS	TIME	
NO DTC IS DETECTED FURTHER TESTING MAY BE REQUIRED.	D .	
L	1	SFA984E

3. A self-diagnostic result is displayed again. If "NO SELF DIAGNOSTIC FAILURE INDICATED" is displayed, check the item first shown on the display.

G
MA
EM

Items shown on display

Faulty system or circuit	Fault detecting conditions			
VEHICLE SPEED SEN	 Input signal does not change for some length of time while driving. Input signal changes abruptly while driving. 	EC		
VERTI G SENSOR F		-		
VERTI G SENSOR R/R	• Voltage is greater than or less than the standard value.	FE		
VERTI G SENSOR R/L				
STEERING ANGLE SEN [ANG SIGNAL] (.a)	Input signal does not change for some length of time while driving at speeds greater than 60 km/h (37 MPH).	AT		
STEERING ANGLE SEN [NEUT SIGNAL] (.b)	 Neutral ("ON") signal is not entered at all while driving a distance of more than 10 km (6 miles). Neutral ("ON") signal is not entered at all when steering wheel is turned at least 360°. Neutral ("ON") signal is entered when steering wheel is turned at least 50°. 	PD		

RA

BR

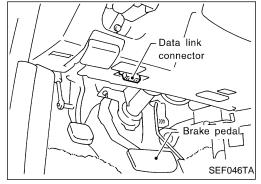
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DIAGNOSIS MODE SELECTION	
SELF-DIAG RESULTS	
DATA MONITOR	
ACTIVE TEST	
ECU PART NUMBER	
	PST412B

DA			EL	UKE					
1.	Connect engine.	CONSULT-II	to	data	link	connector,	then	start	the

MANITAD DDAAEDUDE

Touch "START", "ACT D/SUS" and "DATA MONITOR". 2.

IDX

DATA MONITOR

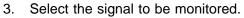
SELECT MONITOR ITEM

ALL SIGNALS

SELECTION FROM MENU

SFA985B





- 1) When "ALL SIGNALS" is selected, touch "START".
- 2) When "SELECTION FROM MENU" is to be selected, touch "SETTING". "MONITOR ITEM MENU" will then be indicated on the display. Touch the item to be monitored, then "ENTER" and "START".
- 3) Print out the data if necessary.

DATA MONITOR MODE

			m selec- on		
Monitored item	Display		Item menu selec- tion	Remarks	
Vehicle speed sensor	VHCL SPEED SE [km/h] or [mph]	0	0	_	
Vertical G sensor front	VERTI G SE F [G]	0	0	_	
Vertical G sensor rear right side	VERTI G SE RR [G]	0	0	_	
Vertical G sensor rear left side	VERTI G SE RL [G]	0	0	_	
Steering angle sensor (steering angle signal) STEERING ANG [°]		0	0	When the battery is disconnected and then reconnected, an abnormal value is displayed until the straight- ahead position (0°) is set during driving.	
Active damper select switch	SELECT SWITCH [AUTO-SPORT]	0	0	—	
Stop lamp switch	STOP LAMP SW [ON-OFF]	0	0	—	
Steering angle sensor (steering neu- tral signal)	NEUTRAL SIG [ON-OFF]	0	0	_	
Damper motor front right	DAMP MTR F/R [Step]	0	0	—	
Damper motor front left	DAMP MTR F/L [Step]	0	0	—	
Damper motor rear right	DAMP MTR R/R [Step]	0	0	—	
Damper motor rear left	DAMP MTR R/L [Step]	0	0	—	
Power steering solenoid valve	POWER STR SOL [A]	0	0	EPS solenoid control current flow from control unit	
Active damper indicator lamp (SPORT)	INDICATOR [ON-OFF]	0	0	_	
Voltage	■ VOLTAGE [V]	_	0	Voltage measured by the voltage probe.	
Pulse	■ PULSE [msec] or [Hz] or [%]	_	0	Pulse width, frequency or duty cycle measured by the pulse probe. Only "#" is displayed if item is unable to be measured. Figures with "#"s are temporary ones. They are the same figures as an actual piece of data which was just previously measured.	

CONSULT-II Inspection Procedure (Cont'd)

Specifications for control unit input and output signals Standard values emitted by CONSULT-II

Output signals refer to the data which are operated by the control unit. If an output circuit (harness) is broken, normal values are displayed.

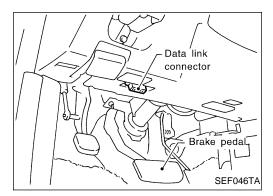
	[Data monitor	Items to check	Reference	
Items to monitor	Conditions	Reference value (when normal)	(when abnormal)	page	MA
VHCL SPEED SE [km/h] or [mph]	During driving or drive wheel rotation	Corresponds with speedometer indication.	Vehicle speed sensor circuit (Refer to "Diag- nostic Procedure 1".)	FA-48	EM
VERTI G SE F [G]	Vehicle is stopped on		Vertical G sensor cir-		
VERTI G SE RR [G]	a flat road.	Within ±0.15G	cuit (Refer to "Diag-	FA-51	LC
VERTI G SE RL [G]			nostic Procedure 4".)		
STEERING ANG [°]	Steering wheel is turned in either direc- tion.	Steering wheel angle from neu- tral is displayed.	Steering angle sensor circuit (Refer to "Diag- nostic Procedure 2".)	FA-49	EC
SELECT SW [AUTO-SPORT]	Select switch position	Set to "AUTO": AUTO Set to "SPORT": SPORT	Select switch circuit (Refer to "Diagnostic Procedure 5".)	FA-52	FE
STOP LAMP SW [ON-OFF]	Brake pedal position	Brake pedal is depressed. : ON Brake pedal is released. : OFF	Stop lamp switch cir- cuit (Refer to "Diag- nostic Procedure 3".)	FA-50	AT
NEUTRAL SIG [ON-OFF]	Steering wheel is set at neutral or is turned in either direction.	Neutral position: ON Other position: OFF	Steering angle sensor circuit (Refer to "Diag- nostic Procedure 2".)	FA-49	PD
DAMP MTR F/R [Step]		16 stop	Shock absorber		FA
DAMP MTR F/L [Step]	Actuator position	16 step	actuator circuit (Refer	FA-54	
DAMP MTR R/R [Step]		16 step	to "Diagnostic Proce-	1 4-34	RA
DAMP MTR R/L [Step]			dure 6".)		
POWER STR SOL [A]	Increase vehicle speed from 0 to 100 km/h (0 to 62 MPH).	0 km/h (0 MPH): Approx. 1.1A 100 km/h (62 MPH): Approx. 0.47A	EPS solenoid circuit (Refer to "Diagnostic Procedure 7" and "Diagnostic Procedure 8".)	FA-57 FA-58	BR ST
INDICATOR [ON-OFF]	Ignition switch is turned to "ON" or engine is operating.	Indicator lamp is on. : ON Indicator lamp is off. : OFF	Indicator lamp circuit (Refer to "Diagnostic Procedure 5".)	FA-52	RS

BT

GI

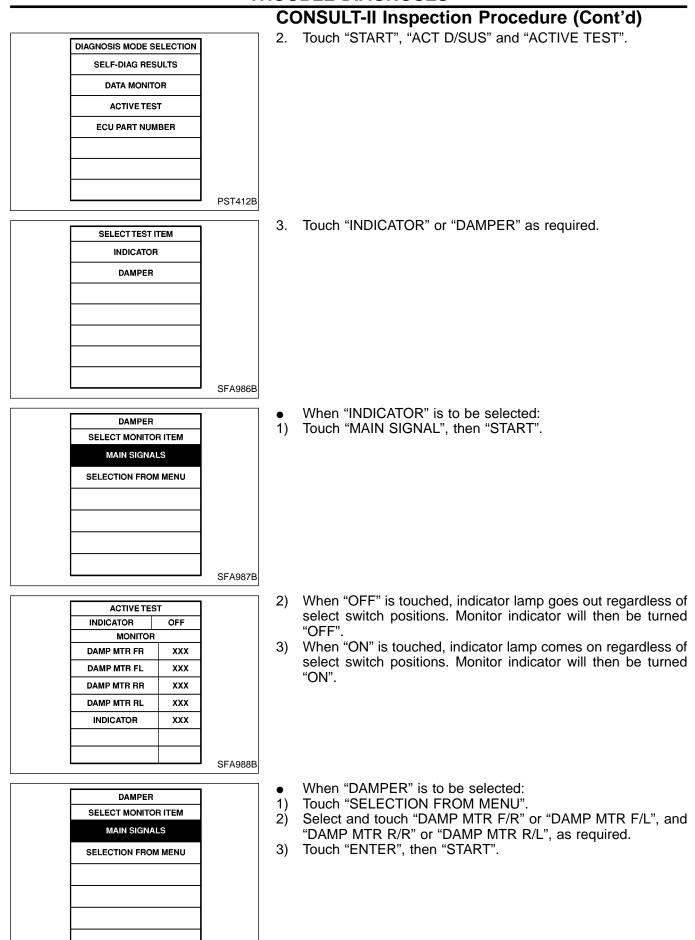
HA

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ACTIVE TEST PROCEDURE

1. Connect CONSULT-II to data link connector, then start the engine.

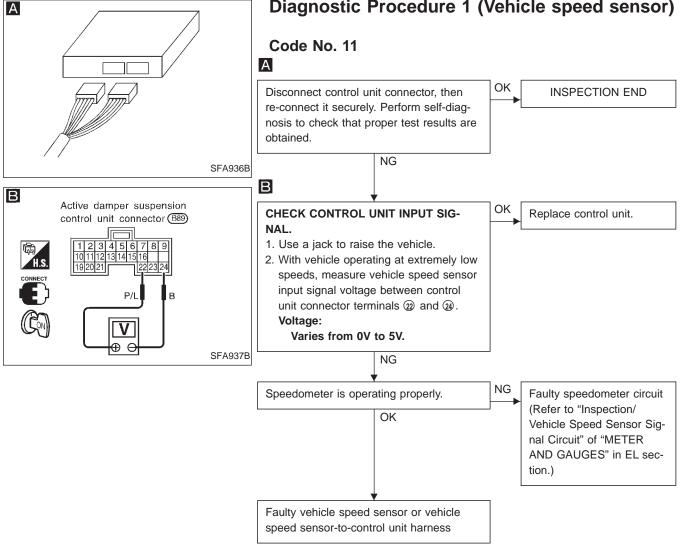


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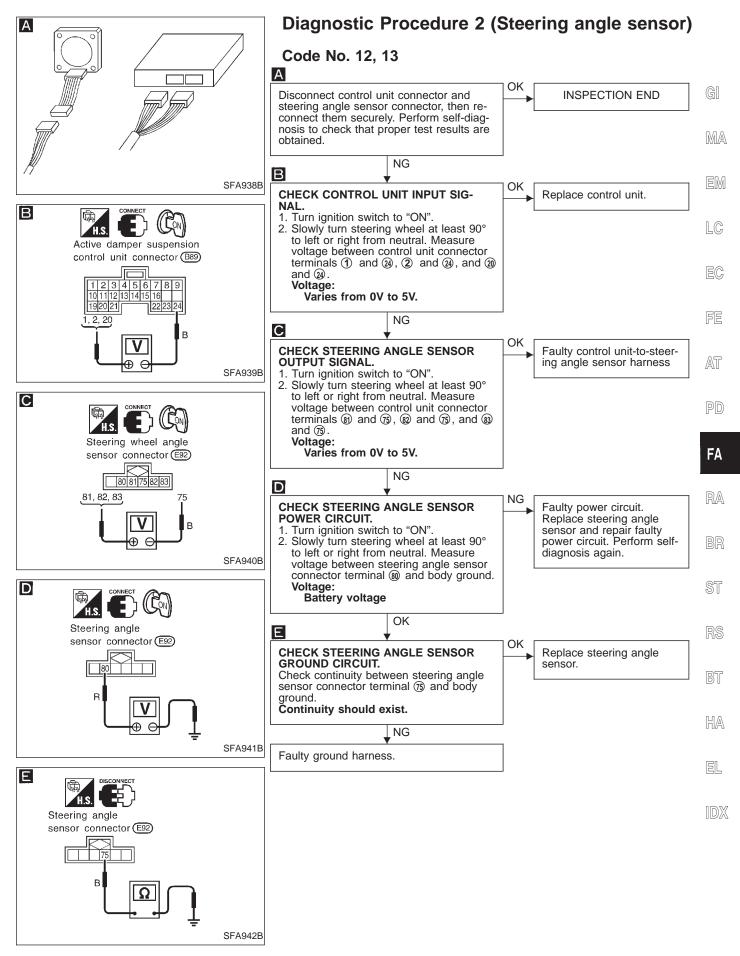
			CC	ONSULT-II Inspection Procedure (Cont'd)	
	E TEST T CONDITION FR-N		4) 5)	"4 step" for front damper motors and "4 step" for rear damper motor will be then shown on the display. Touch "CONDITION CHANGE", "FL-N, FR-N, RL-N, RR-N" and "START".	
RL-N	RR-N				GI
MON	ITOR				
DAMP MTR I					MA
DAMP MTR I	FL XXX				
		SFA989B			EM
ACTIV	ETEST		6)	"96 step" for front damper motors and "96 step" for rear damper	
DAMPER TES	T CONDITION		7)	motor will then appear on the display. Touch "CONDITION CHANGE", "FL-HS, FR-HS, RL-HS,	LC
FL-HS	FR-HS		')	RR-HS" and "START".	EC
RL-HS	RR-HS				E9
DAMP MTR I	ITOR FR XXX				FE
DAMP MTR I					
					AT
		SFA990B			
ACTIV	ETEST		8)	"0 step" for front damper motors and "0 step" for rear damper	PD
DAMPER TES	T CONDITION		9)	motor will then appear on the display. Touch "CONDITION CHANGE" and "FL-SS, FR-SS, RL-SS,	
FL-SS	FR-SS		-)	RR-SS" and "START".	FA
RL-SS	RR-SS				
MON DAMP MTR I	ITOR FR XXX				RA
DAMP MTR					
					BR
		SFA991B			
-			10)	"-40 step" for front damper motors and "-40 step" for rear	ST
	E TEST T CONDITION			damper motor will then appear on the display.	01
FL-SH	FR-SH		11)	Print out data as required.	RS
RL-SH	RR-SH				110
MON	ITOR				BT
DAMP MTR I	R XXX				
DAMP MTR I	FL XXX				HA
		SFA992B			
					EL

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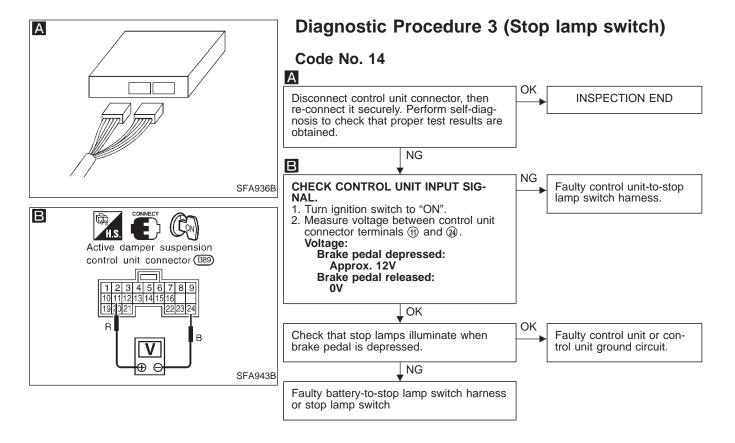


Diagnostic Procedure 1 (Vehicle speed sensor)



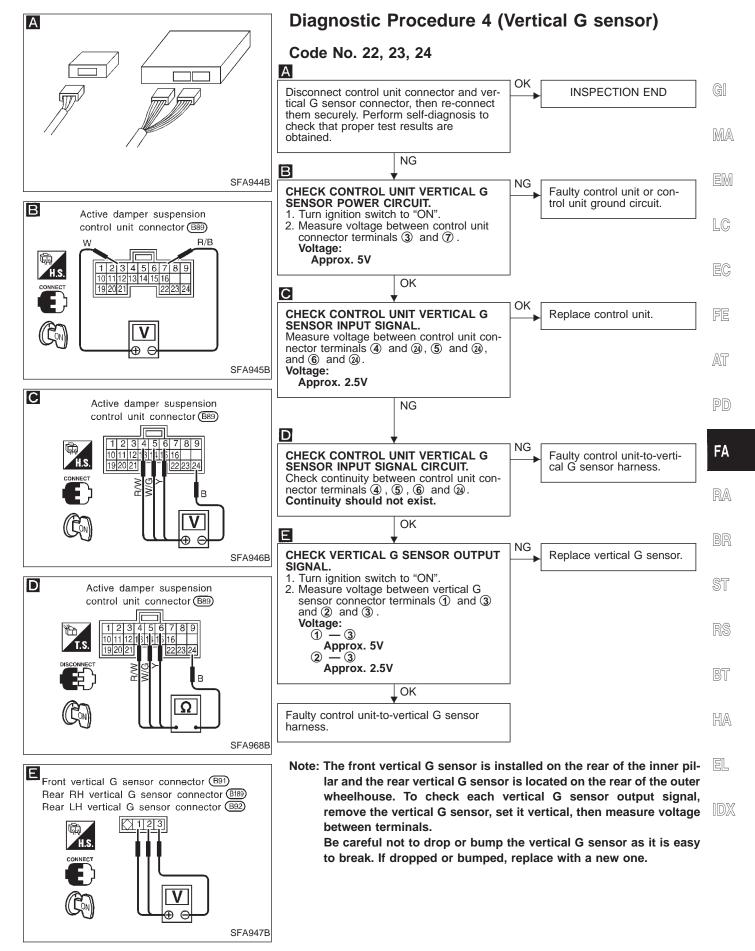
FA-49



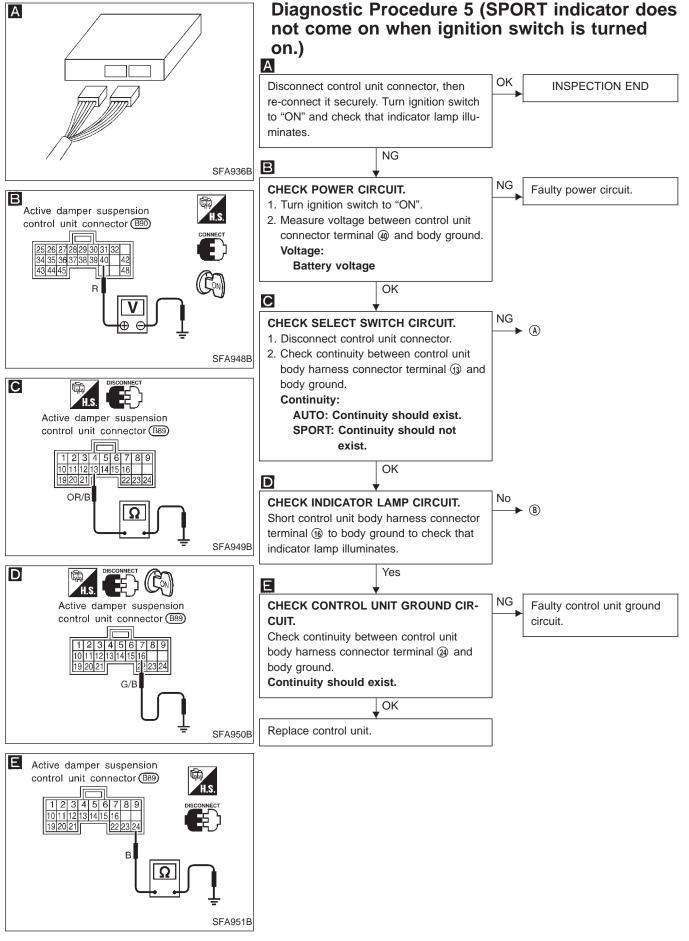


FA-50

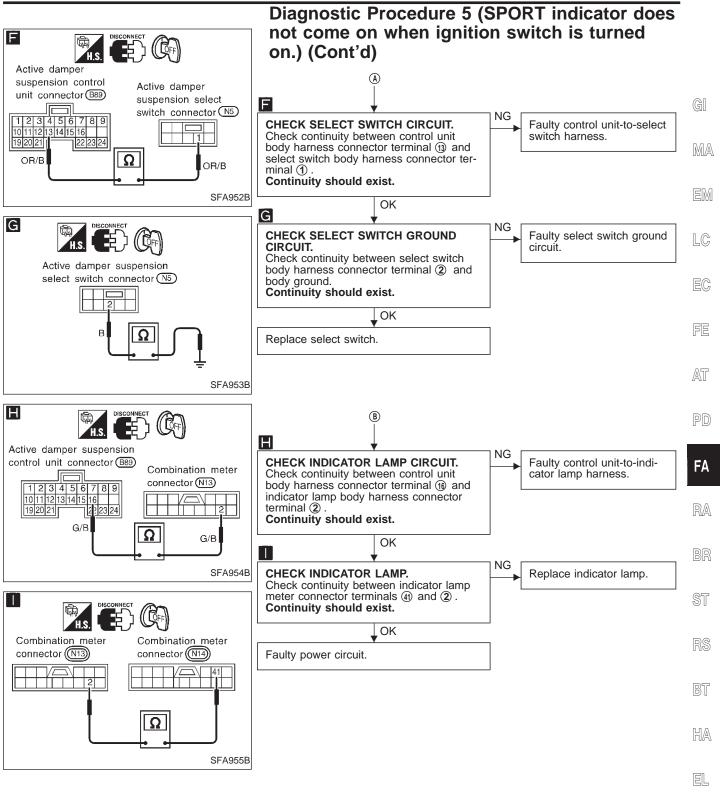






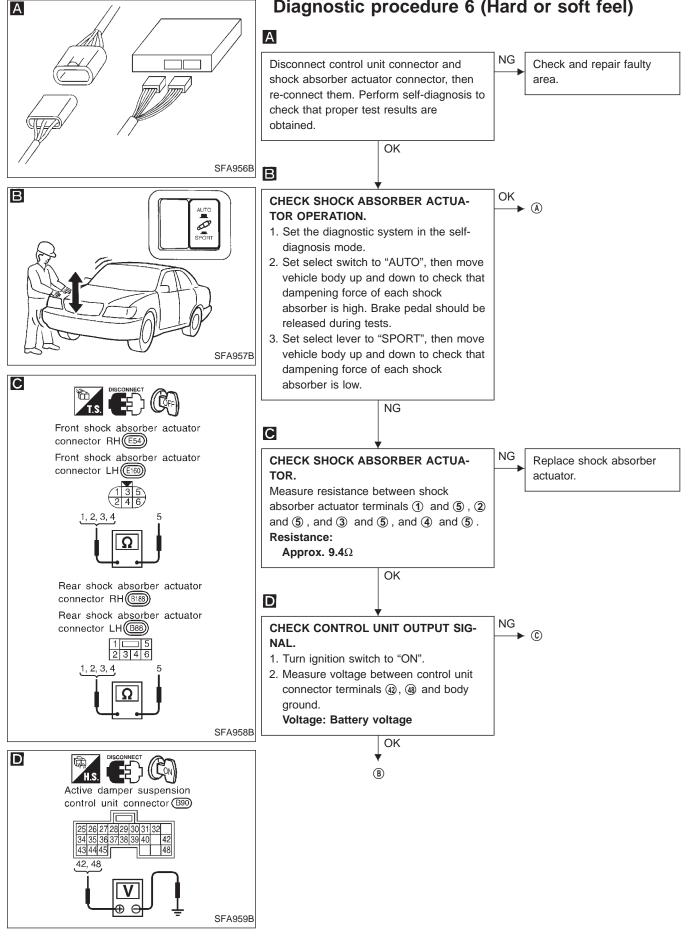


TROUBLE DIAGNOSES FOR SYMPTOMS



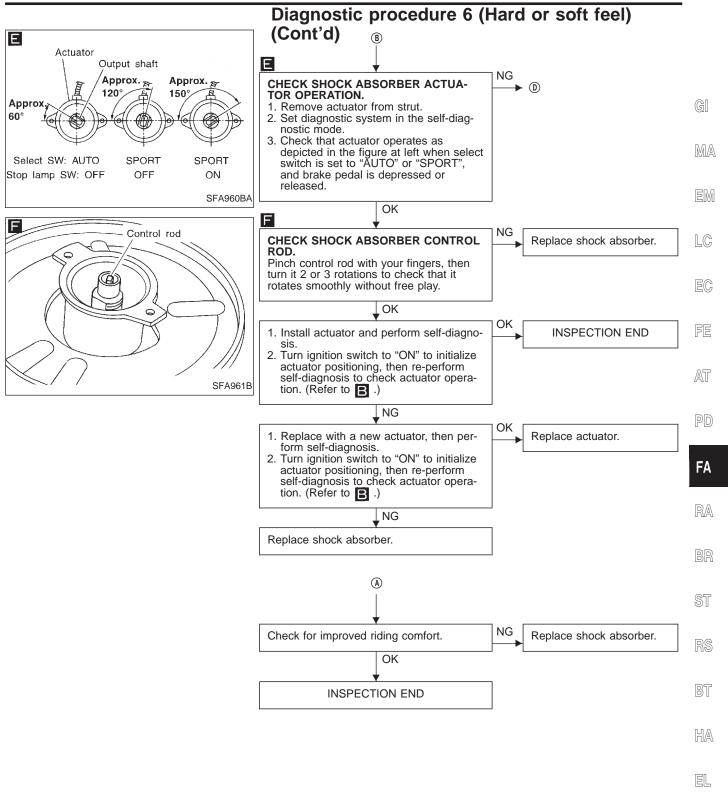
1DX



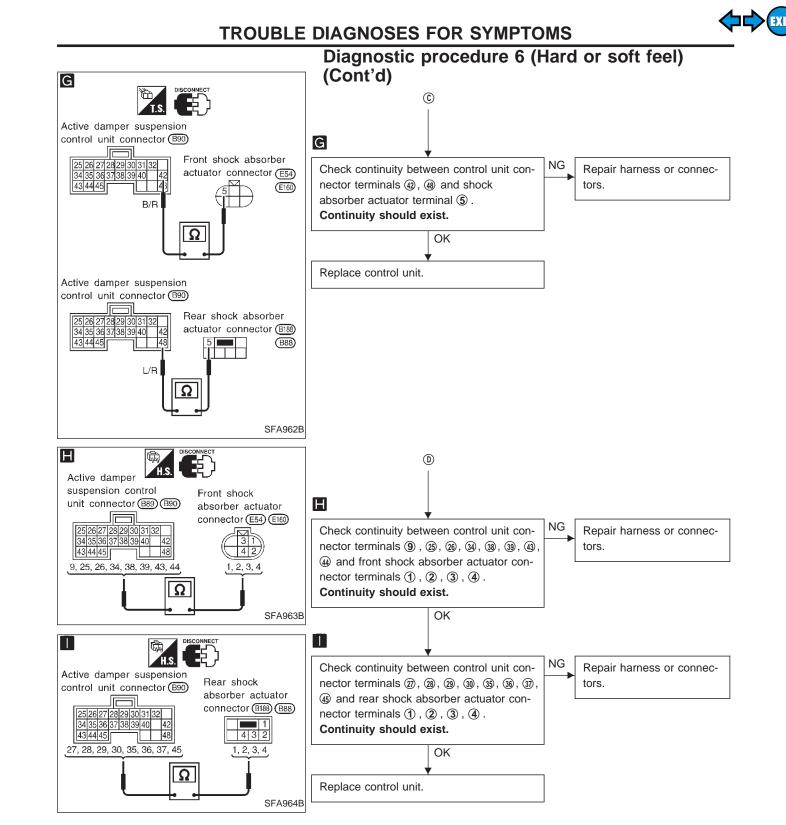


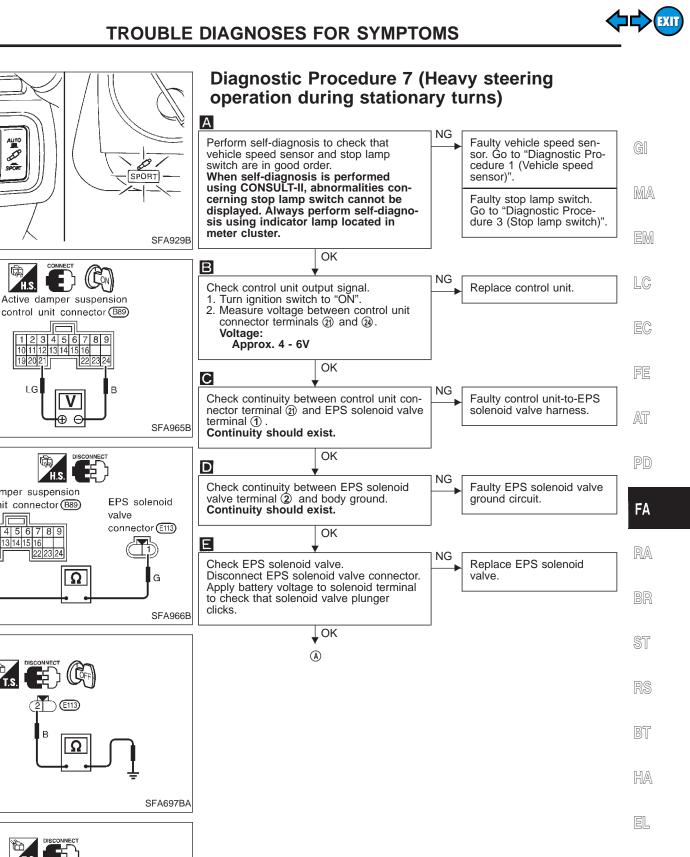
Diagnostic procedure 6 (Hard or soft feel)

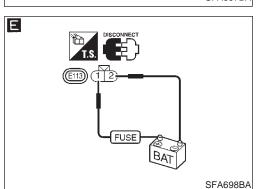
TROUBLE DIAGNOSES FOR SYMPTOMS



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Active damper suspension

control unit connector (B89)

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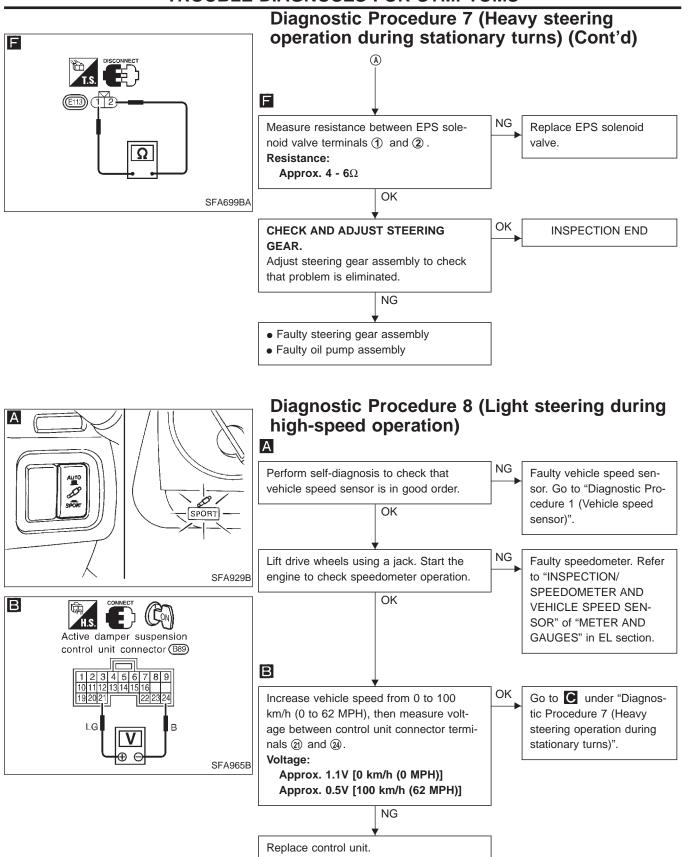
CONNECT

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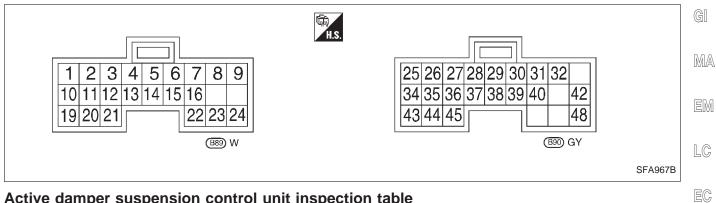
TROUBLE DIAGNOSES FOR SYMPTOMS





Electrical Component Inspection

INSPECTION OF ACTIVE DAMPER SUSPENSION CONTROL UNIT

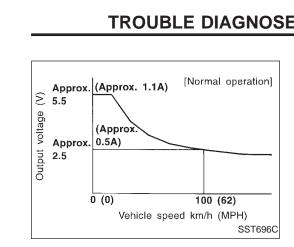


Active damper suspension control unit inspection table

Terminal No.		Dorto to obsolu	Specifications		
+	-	 Parts to check 	Specifi	ICATIONS	
10, 19, 31 32, 40		Power supply	Turn ignition switch "ON"	Battery voltage (Approx. 12V)	
8, 23, 24	-	Ground	-	_	
9, 25, 26 27, 28, 29 30, 34, 35					
36, 37, 38 39, 43, 44 45		Shock absorber actuator	-	_	
42, 48	-		Battery voltage (Approx. 12V)		
13		Select switch	"SPORT" "AUTO"	0V Approx. 5V	
21	Ground	EPS solenoid	At 0 km/h (0 MPH) At 100 km/h (62 MPH)	Approx. 1.1A Approx. 0.47A	
16		Indicator lamp (SPORT)	Select switch set to "SPORT" Select switch set to "AUTO"	0V Battery voltage (Approx. 12V)	
1, 2		Steering angle sensor	Steering wheel slowly turned to either side from neutral	0 to 5V (Approx.) are repeated.	
20			Steering wheel set to neutral	Approx. 5V	
11		Stop lamp switch	Brake pedal released Brake pedal depressed	0V Battery voltage (Approx. 12V)	
3		Vertical G sensor power supply	-	Approx. 5V	
4, 5, 6		Vertical G sensor	Vehicle standstill	Approx. 2.5V	
22]	Vehicle speed sensor	During extremely low speeds	0 to 5V (Approx.) are repeated.	
14, 15	_	CONSULT-II	-	<u> </u>	

TROUBLE DIAGNOSES FOR ACTIVE DAMPER SUSPENSION

Electrical Component Inspection (Cont'd) EPS solenoid valve current flow characteristics





General Specifications

Suspension type	Independent macpherson strut with coil spring
Strut type	Standard: Double-acting hydraulic Optional: Adjusting hydraulic (Active damper suspension)
Stabilizer bar	Standard equipment

Inspection and Adjustment

EM

MA

GI

WHEEL ALIGNMENT (Unladen*1)

Camber			Minimum	-1°25′ (-1.42°)	
			Nominal	-0°40′ (-0.67°)	LC
Degree minute (Decimal degree		Dogroo minuto	Maximum	0°05′ (0.08°)	
		(Decimal degree)	Left and right difference	1° (1.00°) or less	EC
Caster Degree minute (Decimal degree)		Minimum	5°40′ (5.67°)		
		Nominal	6°25′ (6.42°)	FE	
		Degree minute	Maximum	7°10′ (7.17°)	- 66
			Left and right difference	1° (1.00°) or less	
Kingpin inclination Degree minute (Decimal degree		Minimum	12°25′ (12.42°)	AT	
		Degree minute	Nominal	13°10′ (13.17°)	
		(Decimal degree)	Maximum	13°55′ (13.92°)	PD
Total toe-in		Minimum	1 (0.04)		
Distance (A – B) mm (in)		Nominal	2 (0.08)	FA	
		Maximum	3 (0.12)		
	Angle (left plus right) Degree minute		Minimum	4′ (0.07°)	RA
Angle (lef			Nominal	10′ (0.17°)	171/41
		(Decimal degree)	Maximum	16′ (0.27°)	
Wheel turning angle)		Minimum	36°50′ (36.83°)	BR
Insi Full turn*2	Inside		Nominal	39°50′ (39.83°)	
	Degree minute (Decimal degree)	Maximum	40°50′ (40.83°)	ST	
Fuii (um-2	Outside	Degree minute (Decimal degree)	Nominal	32°25′ (32.42°)	RS

*1: Fuel, radiator coolant and engine oil full. Spare tire, jack, hand tools and mats in designated positions.

*2: On power steering models, wheel turning force (at circumference of steering wheel) of 98 to 147 N (10 to 15 kg, 22 to 33 lb) with engine idle.

HA

BT

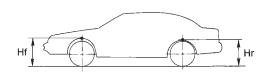
EL



SERVICE DATA AND SPECIFICATIONS (SDS)

Inspection and Adjustment (Cont'd)

WHEELARCH HEIGHT (Unladen*)



Tire		215/60R16	225/50R17
Front (Hf)	mm (in)	731 (28.78)	722 (28.43)
Rear (Hr)	mm (in)	734 (28.90)	723 (28.46)

*: Fuel, radiator coolant and engine oil full. Spare tire, jack, hand tools and mats in designated positions.

WHEEL BEARING

Wheel bearing end play limit	mm (in)	0.05 (0.0020) or less
Wheel bearing lock nut		
Tightening torque	N·m (kg-m, ft-lb)	206 - 284 (21 - 29, 152 - 210)
Maximum wheel bearing prel wheel hub bolt	37.2 (3.8, 8.4)	

LOWER BALL JOINT

Swinging force at cotte	8.8 - 85.3 (0.9 - 8.7, 2.0 - 19.2)	
Turning torque	N·m (kg-cm, in-lb)	0.5 - 4.9 (5 - 50, 4.3 - 43)
Vertical end play	mm (in)	0 (0)

WHEEL RUNOUT (Radial and lateral)

Wheel type		Aluminum wheel	
Radial runout limit	mm (in)	0.3 (0.012) or less	
Lateral runout limit	mm (in)		